



Introduction to Airframe Aeroacoustics Including Applications in Turbulent Flows

William R. Wolf

University of Campinas, Brazil

wolf@fem.unicamp.br

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**Renato Miotto, Tulio Ricciardi, Cristiano Pimenta
Jean Ribeiro, Paulo Azevedo, Mauricio Massarotti**

Sanjiva Lele, Joseph Kochemolayil

Andre Cavalieri, Justin Jaworski

Giridhar Jothiprasad, Lawrence Cheung



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Introdução à Aeroacústica

wolf@fem.unicamp.br

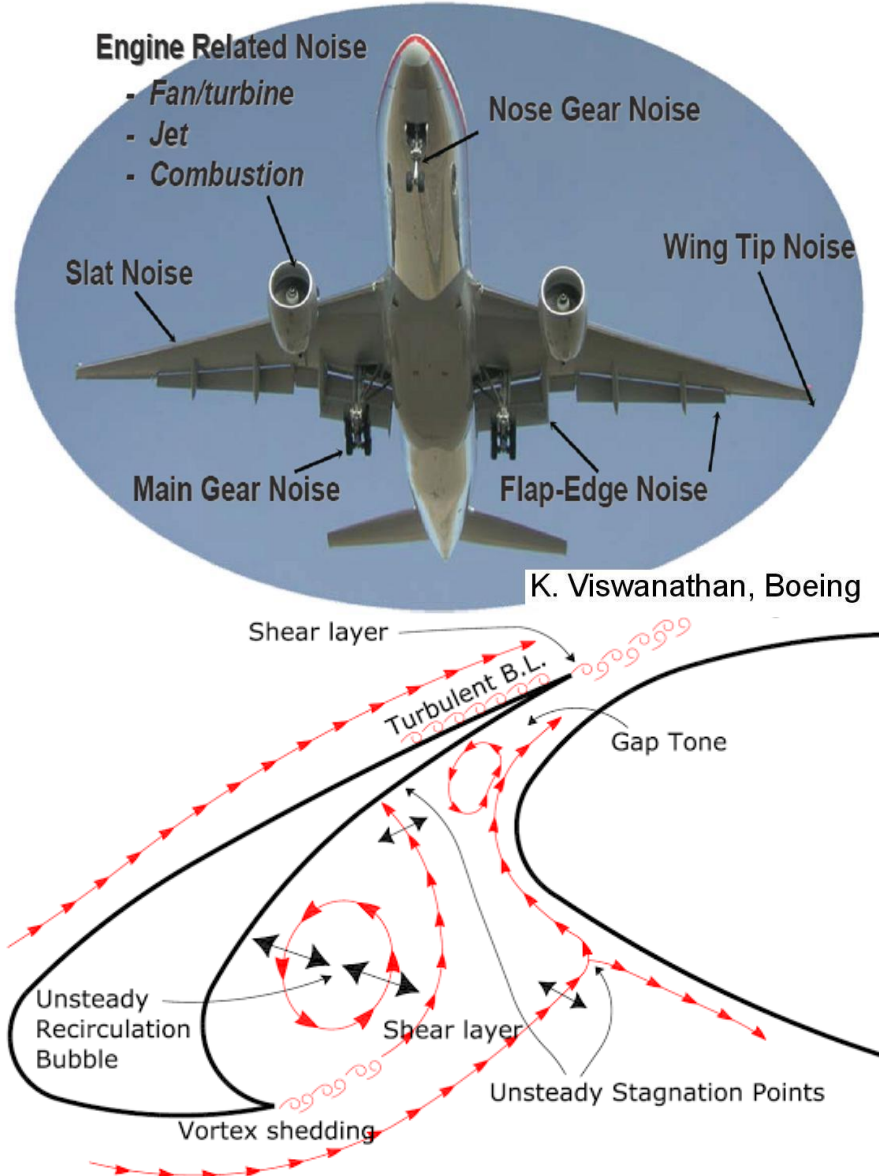
Renato Fuzaro Miotto e William Roberto Wolf
Faculdade de Engenharia Mecânica
Universidade Estadual de Campinas

Aeroacoustics

- Aeroacoustics: field of study that deals with sound generation/propagation in unsteady aerodynamic flows
- Pioneered by Sir James Lighthill in the 50's who was interested in jet noise reduction
- Applications: aircraft, automobiles, wind and gas turbines, musical instruments, fans and rotors, home appliances, etc...



Airframe Noise

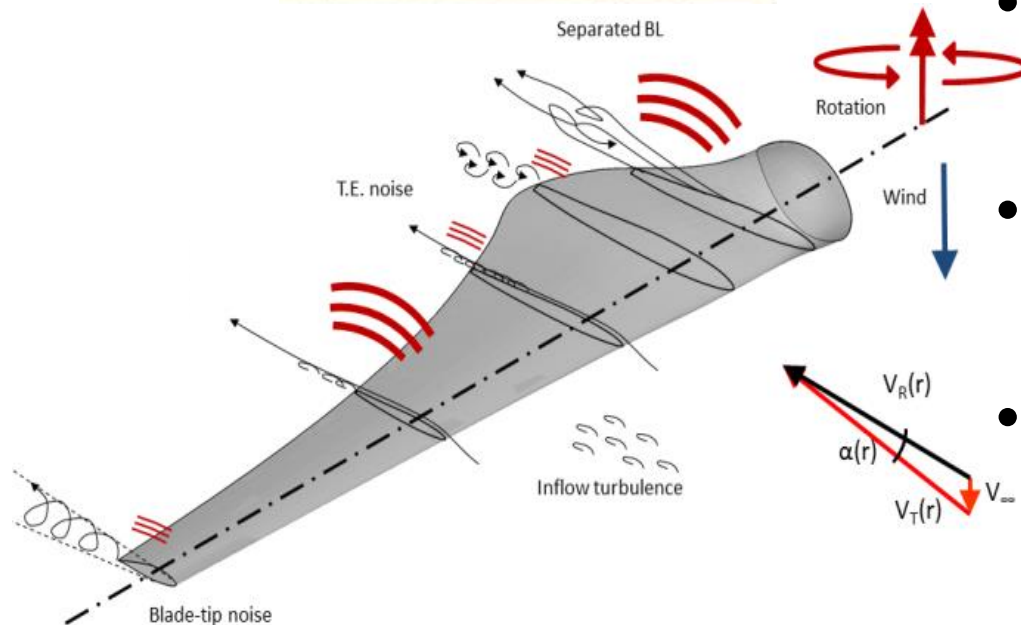


- Jet noise reduction over last decades
- Airframe became an important noise source at landing configuration
- Main sources are high-lift components and landing gears
- Complex flow physics: shear layers, cavities, sharp and blunt bodies, wake interaction, etc...

Wind Turbine Noise

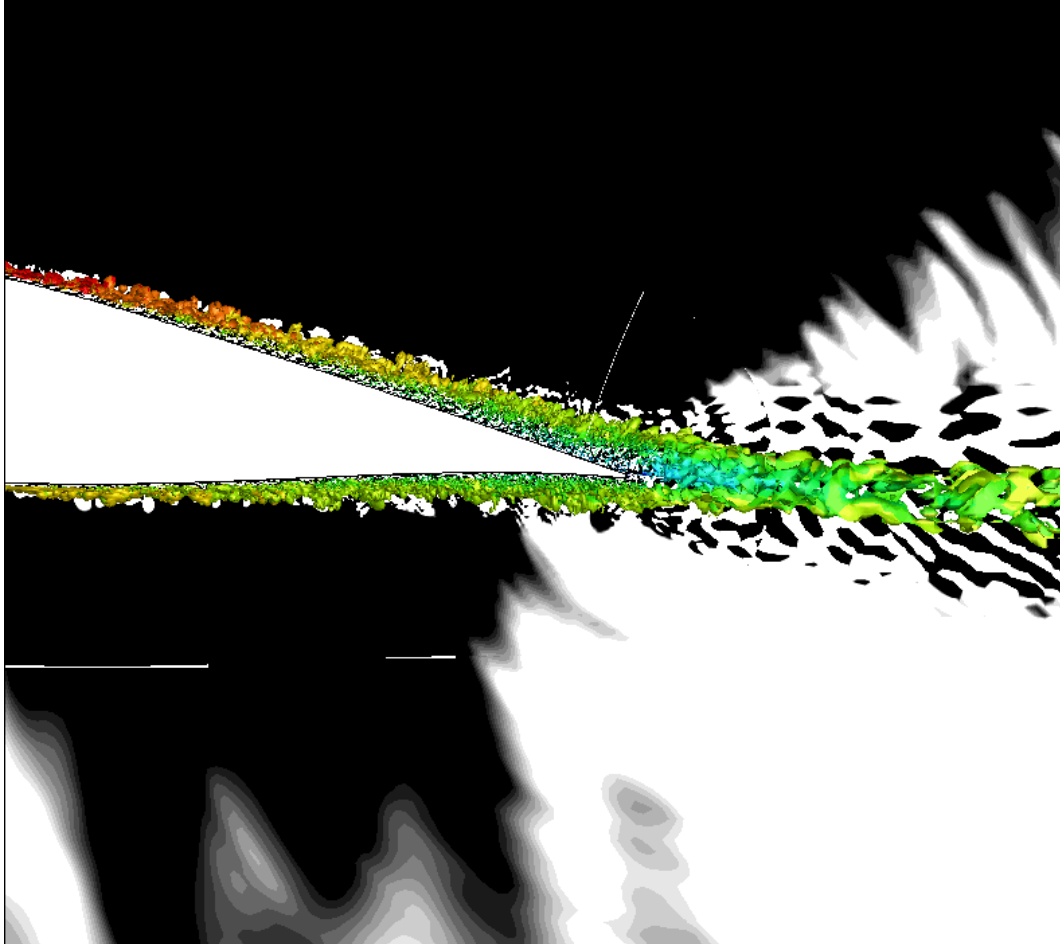


- Regulations on noise generation are more stringent
- Noise is an important factor on wind turbine design
- Airfoil leading-edge noise from inflow turbulence
- Boundary layer trailing-edge noise
- Other sources: stall noise, trailing-edge bluntness noise, etc...



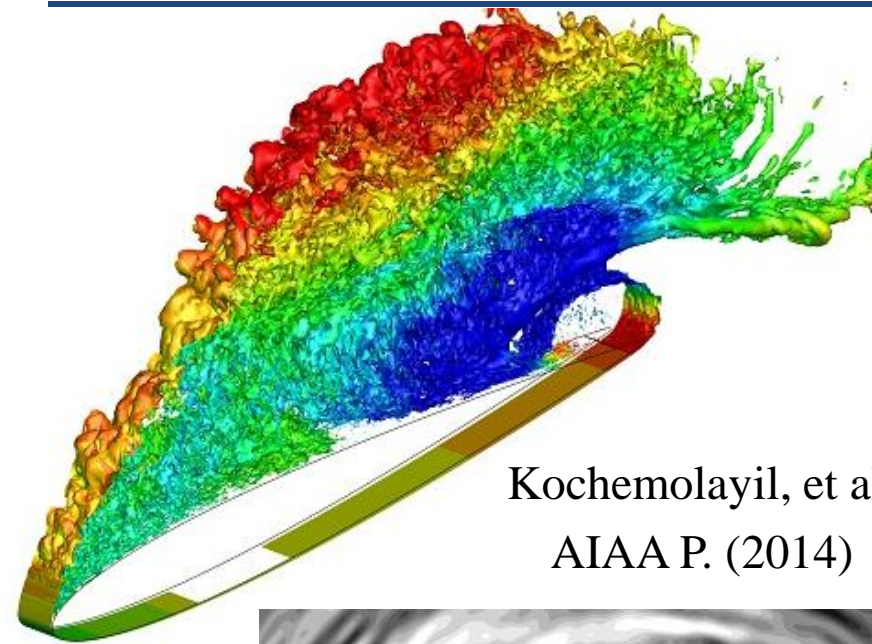
Turbulence and Sound (Noise?)

Wolf et al., AIAA Paper (2012)



- Sound is a by-product of unsteady fluid motions
- Turbulent velocity fluctuations generate noise
- Conversion of hydrodynamic energy into acoustic energy
- Sound propagates as longitudinal waves that vibrate our eardrums

Outline



Kochemolayil, et al.
AIAA P. (2014)



- From the Navier-Stokes eqs. to the wave equation
- Elementary sources
- Some acoustic analogies
- Landing gear noise
- Airfoil noise
- Poro – elastic trailing edges

Fundamentals

Let us start from the Navier-Stokes equations which model unsteady, viscous, compressible flows

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0 \quad \text{Mass}$$

$$\frac{\partial (\rho \mathbf{u})}{\partial t} + \nabla \cdot (\rho \mathbf{u} \mathbf{u} + p \mathbf{I} - \boldsymbol{\sigma}) = 0 \quad \text{Momentum}$$

$$\frac{\partial \rho E}{\partial t} + \nabla \cdot (\rho \mathbf{u} E + p \mathbf{u} - \boldsymbol{\sigma} \cdot \mathbf{u} + \mathbf{q}) = 0 \quad \text{Energy}$$

Closure: ideal gas, Stokes' hypothesis, Fourier's law, Gibbs equation

Fundamentals

- For many applications sound is linear
 - absence of non-linear interactions among waves
 - superposition of solutions is allowed
- Viscous effects can be neglected
 - acoustic Reynolds numbers are quite high for most frequencies of interest

$$\frac{\partial \rho'}{\partial t} + \rho_0 \nabla \cdot \mathbf{u}' = m'$$

$$c_0^2 = \left(\frac{\partial p}{\partial \rho} \right)_s$$

$$\rho_0 \frac{\partial \mathbf{u}'}{\partial t} + \nabla p' = \mathbf{F}$$

$$\rho' = p' / c_0^2$$

Fundamentals

Wave equation for pressure fluctuation

$$\begin{aligned} \frac{\partial}{\partial t} \left(\frac{\partial \rho'}{\partial t} + \rho_0 \nabla \cdot \mathbf{u}' \right) &= \frac{\partial m'}{\partial t} \\ \nabla \cdot \left(\rho_0 \frac{\partial \mathbf{u}'}{\partial t} + \nabla p' \right) &= \nabla \cdot (\mathbf{F}) \end{aligned} \quad \begin{array}{c} \searrow \\ \text{subtract} \\ \nearrow \end{array} \quad \left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) p' = \frac{\partial m'}{\partial t} - \nabla \cdot \mathbf{F}$$

$$\hat{p}'(\mathbf{x}, \omega) = \int_{-\infty}^{\infty} p'(\mathbf{x}, t) e^{i\omega t} dt$$

Fourier transform

$$\nabla^2 \hat{p}' + k^2 \hat{p}' = i\omega \hat{m}' - \nabla \cdot \hat{\mathbf{F}}$$

Helmholtz equation

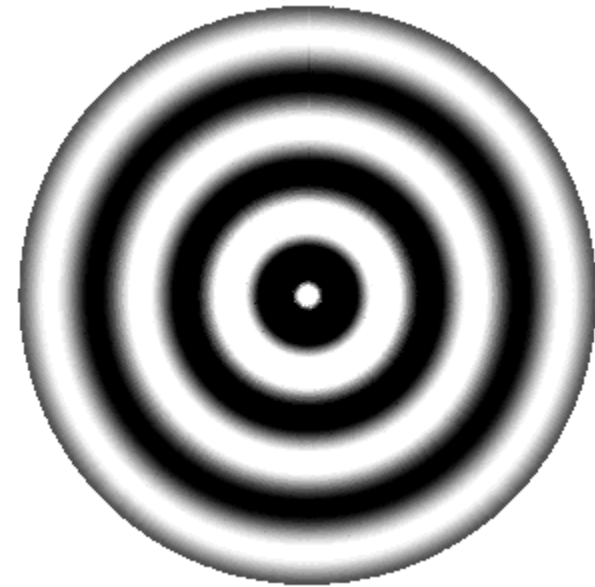
Elementary Sources

In practical problems of engineering, noise sources can be modeled using elementary sources

Monopole sources: mass injection, unsteady heat addition

$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) p' = -q(\tau) \delta(\mathbf{x} - \mathbf{y})$$

$$p'(\mathbf{x}, t) = -\frac{1}{4\pi} \int_{-\infty}^{\infty} \frac{q(\mathbf{y}, t - \frac{\|\mathbf{x} - \mathbf{y}\|}{c_0})}{\|\mathbf{x} - \mathbf{y}\|} d^3\mathbf{y}$$



Point monopole

Elementary Sources

Dipole sources: unsteady surface loading

$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) p' = \mathbf{F}(\tau, \mathbf{y}) = -\nabla \cdot [\mathbf{f}(\tau) \delta(\mathbf{y})]$$

$$p'(\mathbf{x}, t) = \int_{-\infty}^{\infty} \frac{\partial}{\partial y_j} \frac{f_j(\mathbf{y}, t - \|\mathbf{x} - \mathbf{y}\|/c_0)}{4\pi \|\mathbf{x} - \mathbf{y}\|} d^3\mathbf{y}$$

Since $\partial/\partial y_j = -\partial/\partial x_j$

$$p'(\mathbf{x}, t) = -\frac{\partial}{\partial x_j} \int_{-\infty}^{\infty} \frac{f_j(\mathbf{y}, t - \|\mathbf{x} - \mathbf{y}\|/c_0)}{4\pi \|\mathbf{x} - \mathbf{y}\|} d^3\mathbf{y}$$



Point dipole

Elementary Sources

For a point dipole one has:

$$\frac{\partial}{\partial x_j} \left(\frac{f_j(\mathbf{y}, t - \frac{\|\mathbf{x} - \mathbf{y}\|}{c_0})}{4\pi \|\mathbf{x} - \mathbf{y}\|} \right) = \frac{1}{4\pi \|\mathbf{x} - \mathbf{y}\|} \frac{\partial}{\partial x_j} (f_j(\mathbf{y}, t - \|\mathbf{x} - \mathbf{y}\|/c_0)) + f_j(\mathbf{y}, t - \|\mathbf{x} - \mathbf{y}\|/c_0) \frac{\partial}{\partial x_j} \left(\frac{1}{4\pi \|\mathbf{x} - \mathbf{y}\|} \right)$$

which finally gives:

$$p'(\mathbf{x}, t) = \frac{\cos\theta}{4\pi} \left(\underbrace{\frac{\partial f_j}{\partial t} \frac{1}{c_0 \|\mathbf{x} - \mathbf{y}\|}}_{\text{far-field}} + \underbrace{\frac{f_j}{\|\mathbf{x} - \mathbf{y}\|^2}}_{\text{near-field}} \right)$$

$$\cos\theta = (\mathbf{x} - \mathbf{y})/\|\mathbf{x} - \mathbf{y}\| \quad \text{dipoles are directive}$$

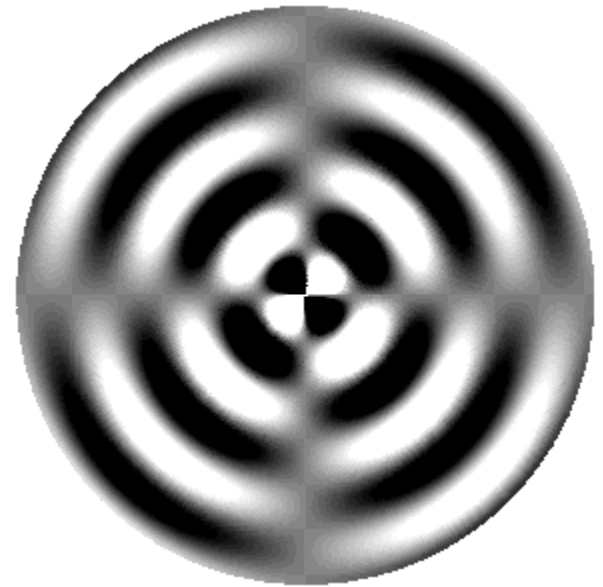
Elementary Sources

Quadrupole sources: turbulence

$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) p' = \frac{\partial^2 T_{ij}}{\partial y_i \partial y_j}(\mathbf{y}, \tau)$$

Quadrupole sources are less efficient noise sources (than dipoles and monopoles) due to cancelation

$$p'(\mathbf{x}, t) = \frac{1}{4\pi} \frac{\partial^2}{\partial x_i \partial x_j} \int_{-\infty}^{\infty} \frac{T_{ij}(\mathbf{y}, t - \|\mathbf{x} - \mathbf{y}\|/c_0)}{\|\mathbf{x} - \mathbf{y}\|} d^3\mathbf{y}$$



Point lateral quadrupole

Lighthill's Acoustic Analogy

- Aerodynamic noise can be predicted by the direct solution of the Navier-Stokes equations
- However, solving a wave equation is easier!
- Lighthill showed that a re-arrangement of the Navier-Stokes equations leads to:

$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) (c_0^2 \rho') = \frac{\partial^2 T_{ij}}{\partial y_i \partial y_j}$$

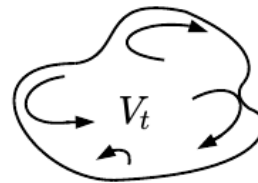
$$T_{ij} = \rho u_i u_j + (p' - c_0^2 \rho') \delta_{ij} - \sigma_{ij}$$

Lighthill's Acoustic Analogy

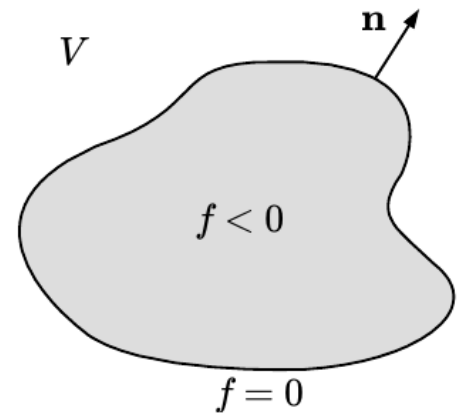
- Lighthill's analogy models a complex flow process using an equivalent source
- How useful is this new equation? Is it simpler than solving the Navier-Stokes equations? How can we solve it?
- The Navier-Stokes equations need to be solved anyway through experiments, numerical simulation or using analytical models
- In general, the sound sources are limited to the turbulent flow region

Curle's Analogy

- Acoustic analogies for airframe noise problems
- Curle extended Lighthill's analogy to account for noise generation by solid surfaces immersed in turbulent flows



$f > 0$



$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) (H c_0^2 \rho') =$$

$$\underbrace{\frac{\partial}{\partial t} \left(\rho u_j \frac{\partial H}{\partial x_j} \right)}_{\text{monopole}} - \underbrace{\frac{\partial}{\partial x_i} \left((\rho u_i u_j + p'_{ij}) \frac{\partial H}{\partial x_j} \right)}_{\text{dipole}} + \underbrace{\frac{\partial^2 (H T_{ij})}{\partial x_i \partial x_j}}_{\text{quadrupole}}$$

Curle's Analogy

Solution of Curle's analogy includes volumetric and surface sources

$$H c_0^2 \rho' = \frac{\partial^2}{\partial x_i \partial x_j} \int_V \frac{T_{ij}}{4\pi ||\mathbf{x} - \mathbf{y}||} d^3\mathbf{y} + \frac{\partial}{\partial t} \oint_S \frac{\rho u_j}{4\pi ||\mathbf{x} - \mathbf{y}||} dS_j(\mathbf{y}) \\ - \frac{\partial}{\partial x_i} \oint_S \frac{\rho u_i u_j + p \delta_{ij} - \sigma_{ij}}{4\pi ||\mathbf{x} - \mathbf{y}||} dS_j(\mathbf{y})$$

Surface can be a solid body immersed in turbulent flow or a “permeable” flow region

Curle's Analogy

- For low Mach number flows, quadrupole sources can be neglected (w.r.t. to dipoles)
- Considering a surface surrounding a solid body

$$H c_0^2 \rho' = - \frac{\partial}{\partial x_j} \oint_S \frac{p'}{4\pi ||\mathbf{x} - \mathbf{y}||} dS_j(\mathbf{y})$$

- Assuming a compact body ($L \ll \lambda$) and a far-field observer

$$c_0^2 \rho'(\mathbf{x}, t) \approx \frac{-x_j}{4\pi c_0 ||\mathbf{x}||^2} \frac{\partial}{\partial t} \oint_S p' \left(\mathbf{y}, t - \frac{||\mathbf{x}||}{c_0} + \frac{\mathbf{x} \cdot \mathbf{y}}{c_0 ||\mathbf{x}||} \right) n_j dS(\mathbf{y})$$

Ffowcs Williams and Hawking's Analogy

- FW&H extended Curle's analogy: observers, sources and control surfaces can move

$$\left(\frac{\partial^2}{\partial t^2} - c_0^2 \nabla^2 \right) (H \rho') = \frac{\partial^2 (H T_{ij})}{\partial x_i \partial x_j} + \frac{\partial}{\partial t} \left\{ [\rho(u_i - v_i) + \rho_0 v_i] \frac{\partial f}{\partial x_i} \delta(f) \right\} -$$

FW&H equation

$$\frac{\partial}{\partial x_i} \left\{ [\rho u_i (u_j - v_j) + p \delta_{ij} - \sigma_{ij}] \frac{\partial f}{\partial x_j} \delta(f) \right\}$$

$$H c_0^2 \rho'(\mathbf{x}, t) = H p'(\mathbf{x}, t) = \frac{\partial^2}{\partial x_i \partial x_j} \int_V \frac{H T_{ij} \delta(t - \tau - \|\mathbf{x} - \mathbf{y}\|/c_0)}{4\pi \|\mathbf{x} - \mathbf{y}\|} d^3 \mathbf{y} d\tau -$$

$$\frac{\partial}{\partial x_i} \int_V \frac{[\rho u_i (u_j - v_j) + p' \delta_{ij} - \sigma_{ij}]}{4\pi \|\mathbf{x} - \mathbf{y}\|} \frac{\partial f}{\partial x_j} \delta(f) \delta \left(t - \tau - \frac{\|\mathbf{x} - \mathbf{y}\|}{c_0} \right) d^3 \mathbf{y} d\tau +$$

$$\frac{\partial}{\partial t} \int_V \frac{[\rho (u_j - v_j) + \rho_0 v_j]}{4\pi \|\mathbf{x} - \mathbf{y}\|} \frac{\partial f}{\partial x_j} \delta(f) \delta \left(t - \tau - \frac{\|\mathbf{x} - \mathbf{y}\|}{c_0} \right) d^3 \mathbf{y} d\tau$$

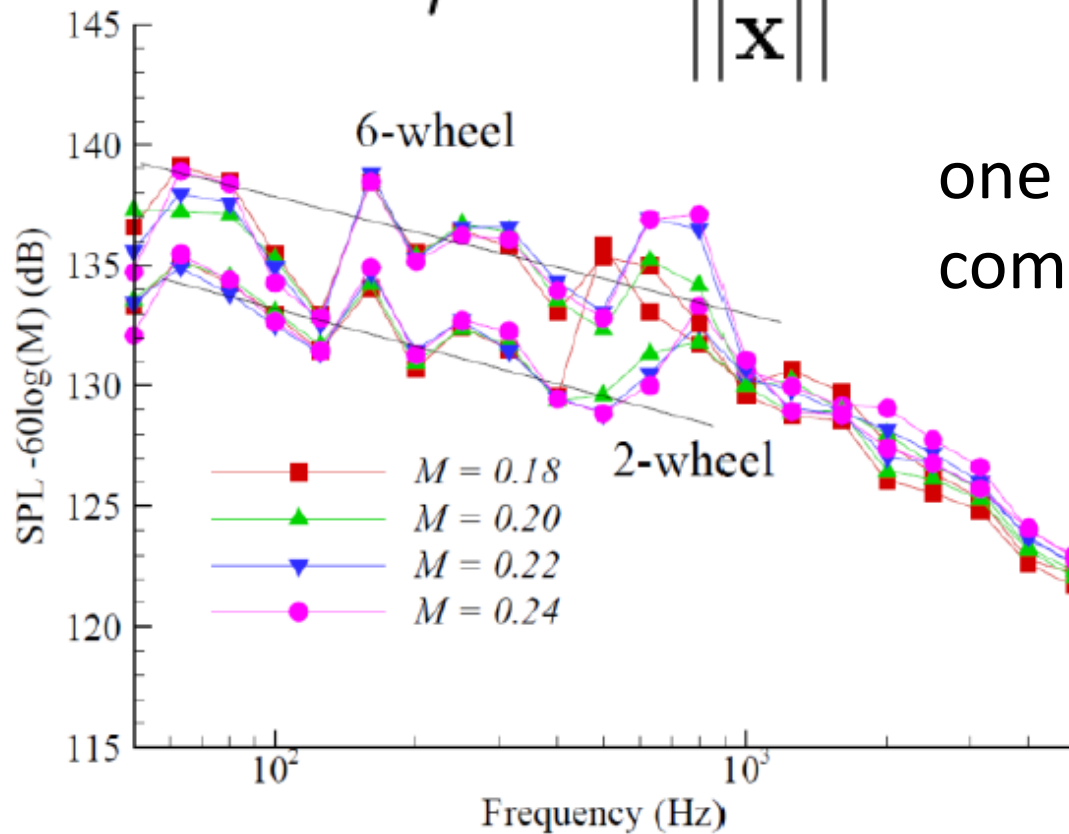
Curle's Analogy

From Curle's analogy, for compact bodies

$$\rho' \sim \frac{\rho_0 M^3 L}{||\mathbf{x}||}$$

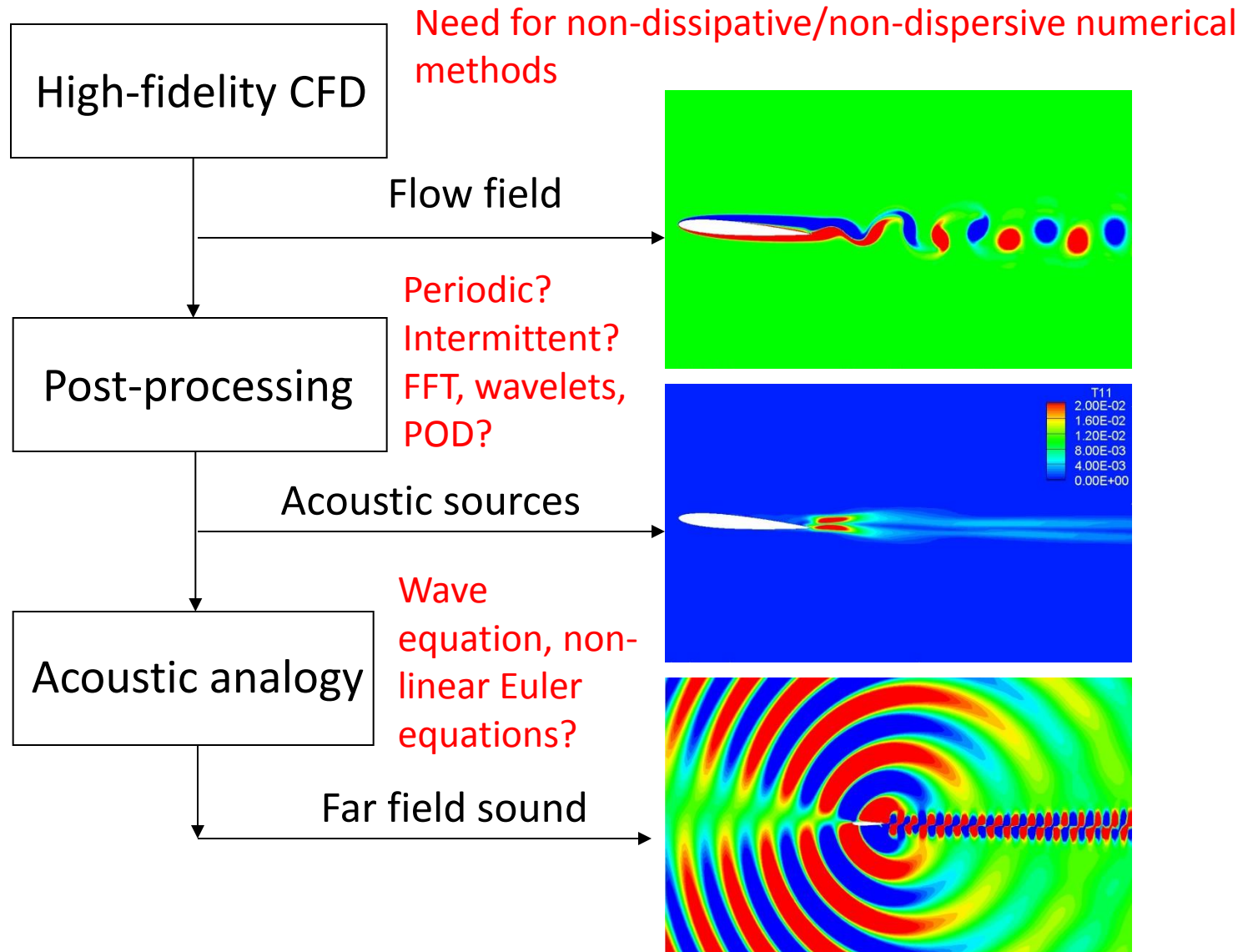
$$\Rightarrow \bar{p}'^2 \sim M^6$$

one should remind that for compact quadrupoles $\bar{p}'^2 \sim M^8$



Results from Guo *et al.* (2004) for noise scaling of 2- and 6-wheel landing gears

Hybrid Method for Noise Prediction

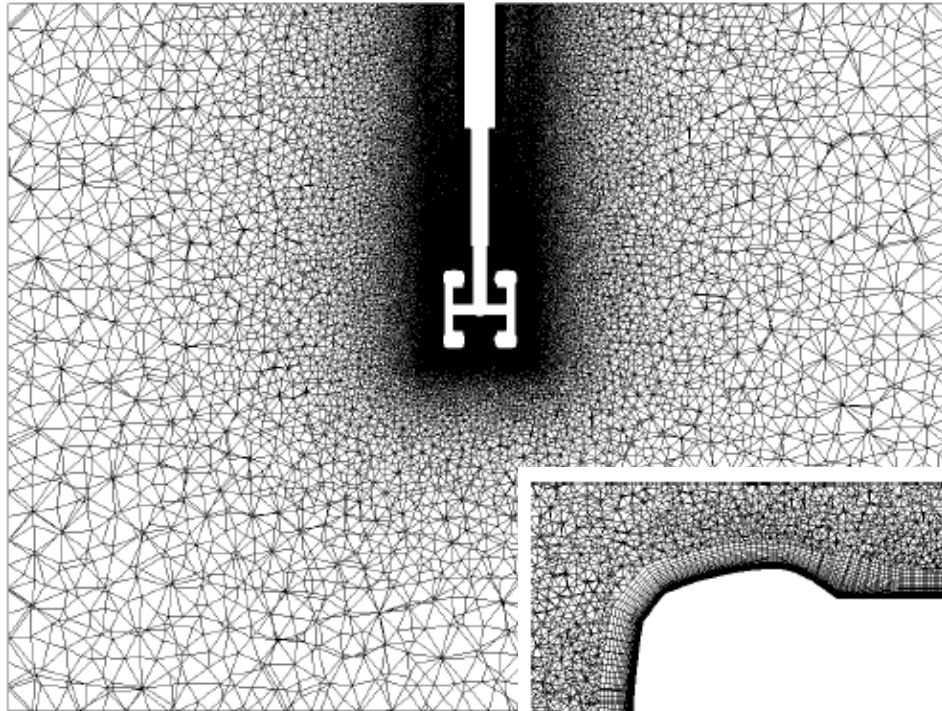


Landing Gear Noise Prediction

Landing Gear Noise Prediction

- Detached eddy simulation (DES): BCFD code
 - hybrid unstructured mesh (finite volume)
 - second order spatial discretization using HLLE plus bounded central difference
 - Barth-Jespersen flux limiter
 - dual time stepping with implicit line Gauss-Seidel scheme for pseudo time and optimized mixed 2nd - 3rd order backward-differencing formulation for physical time step
 - SA turbulence model on RANS regions

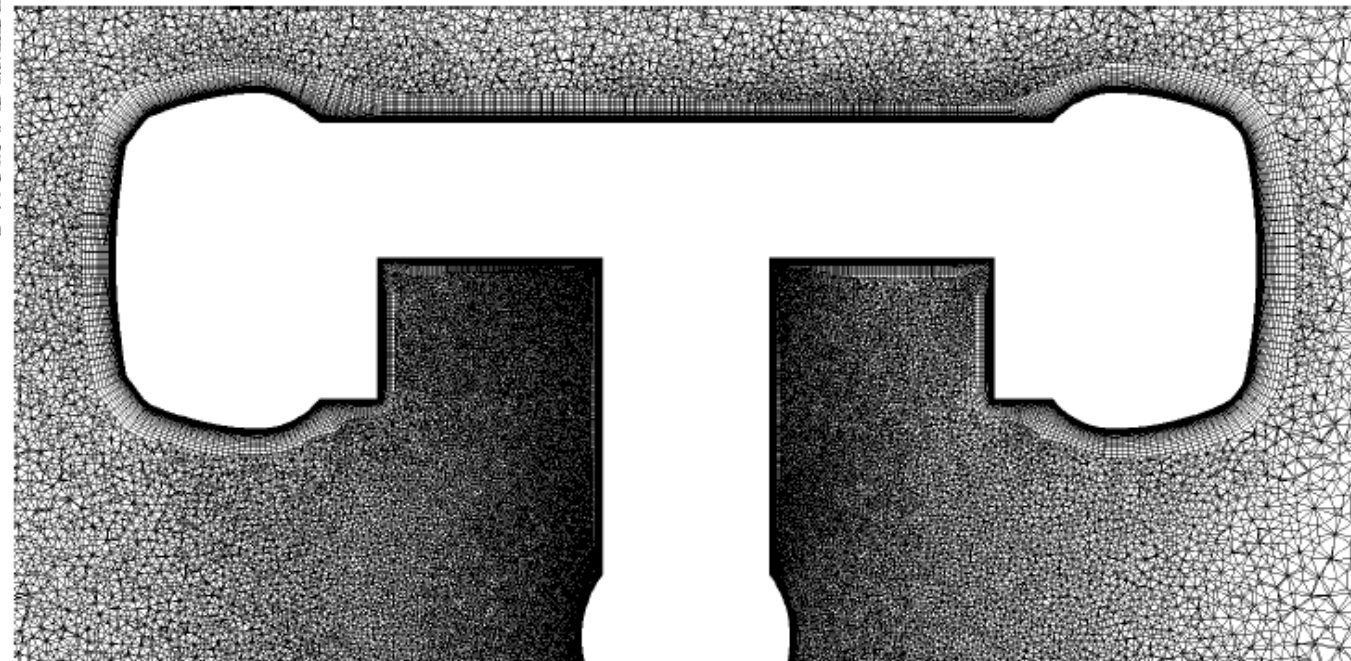
Landing Gear Noise Prediction



Mesh with approx. 100 million volumes

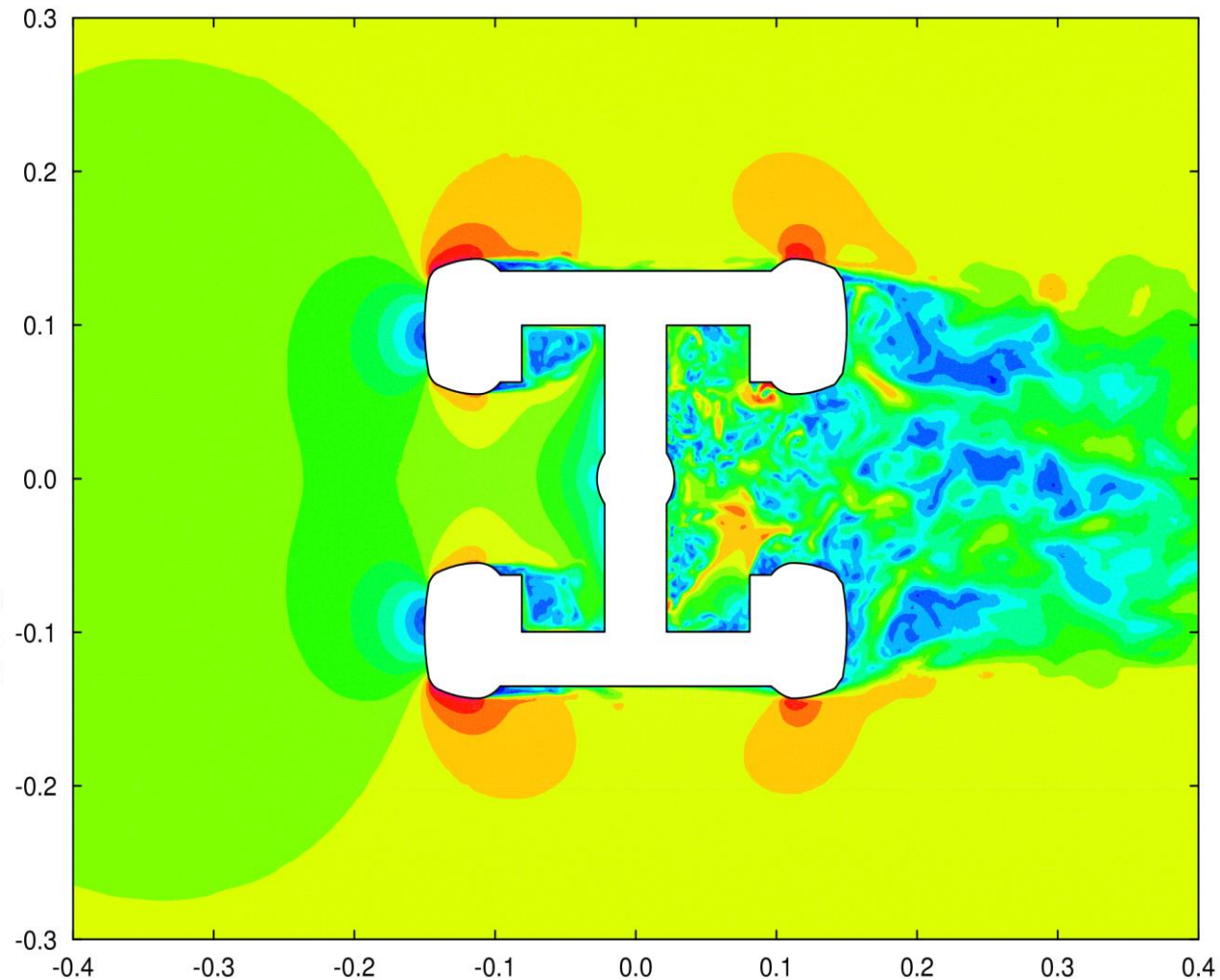
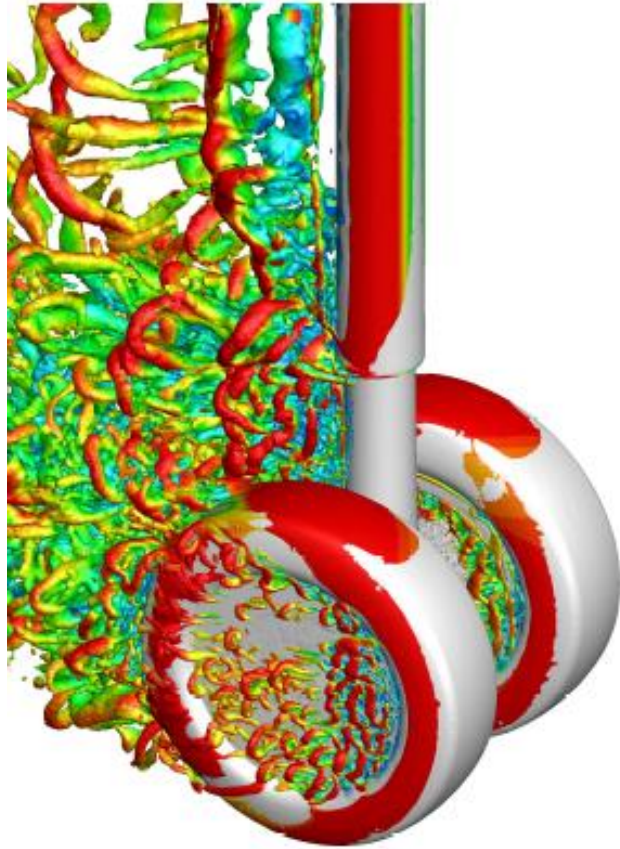
Boundary layers: prism elements

Wakes: tetrahedral elements

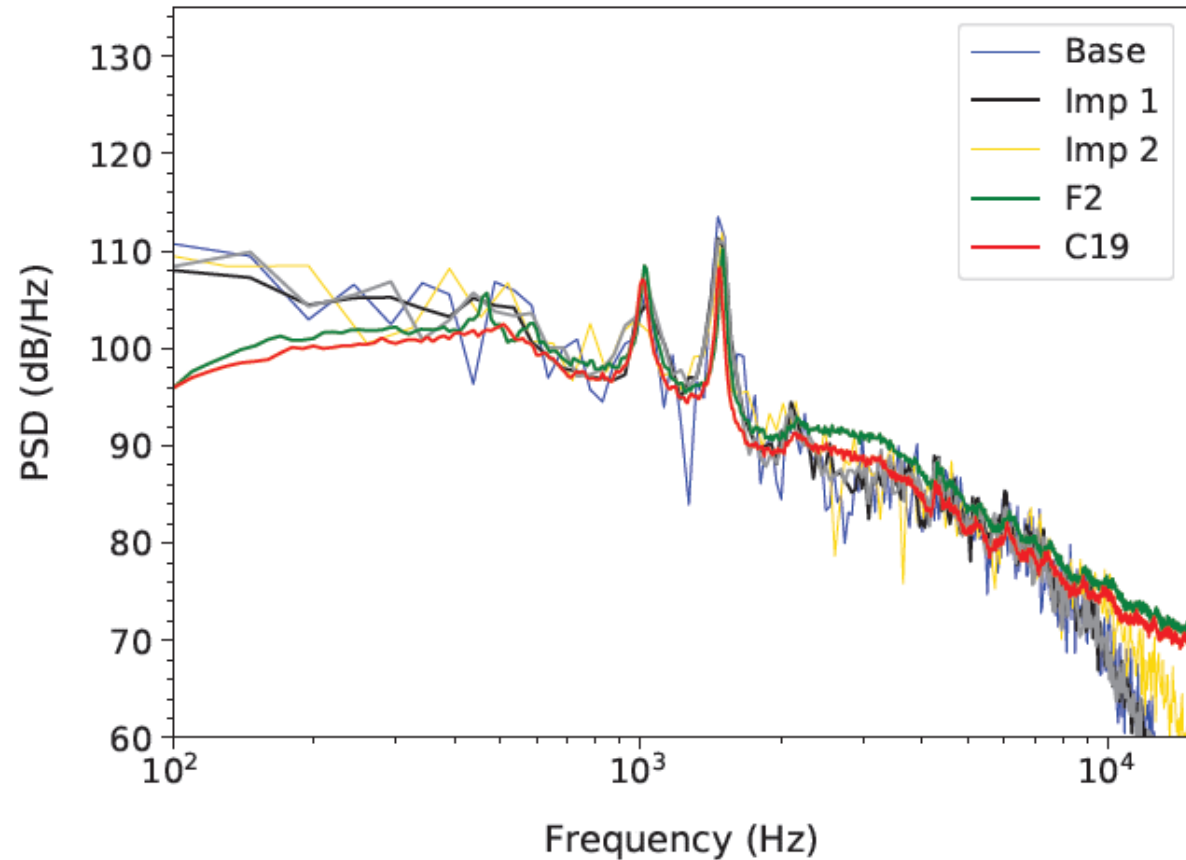
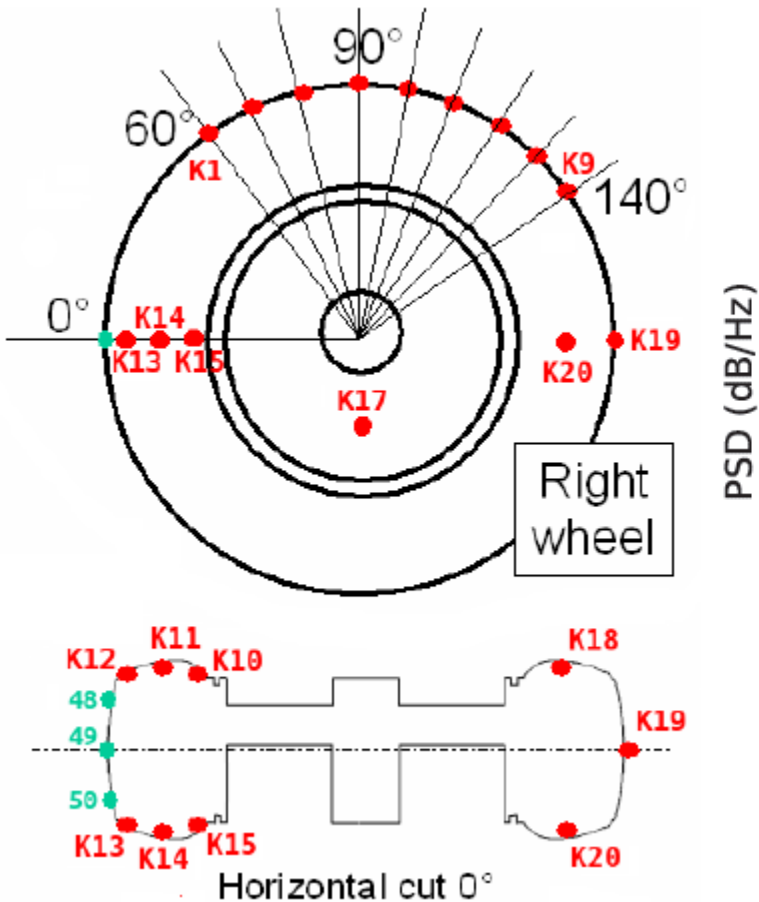


Landing Gear Noise Prediction

LAGOON landing gear DES by Ricciardi, *et al.* (2017)



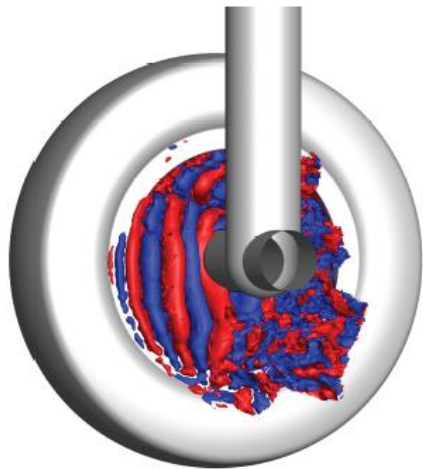
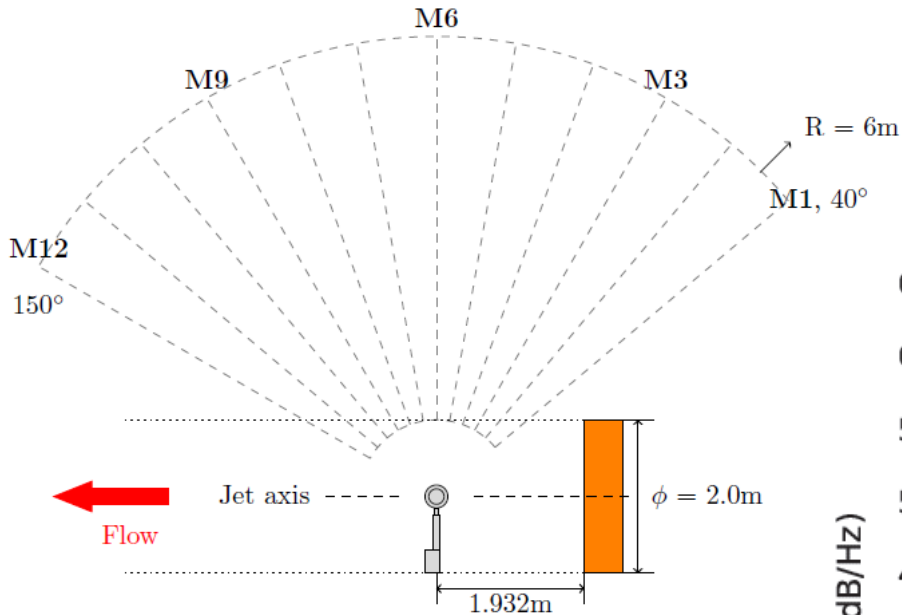
Landing Gear Noise Prediction



Near-field surface pressure
(K15 probe)

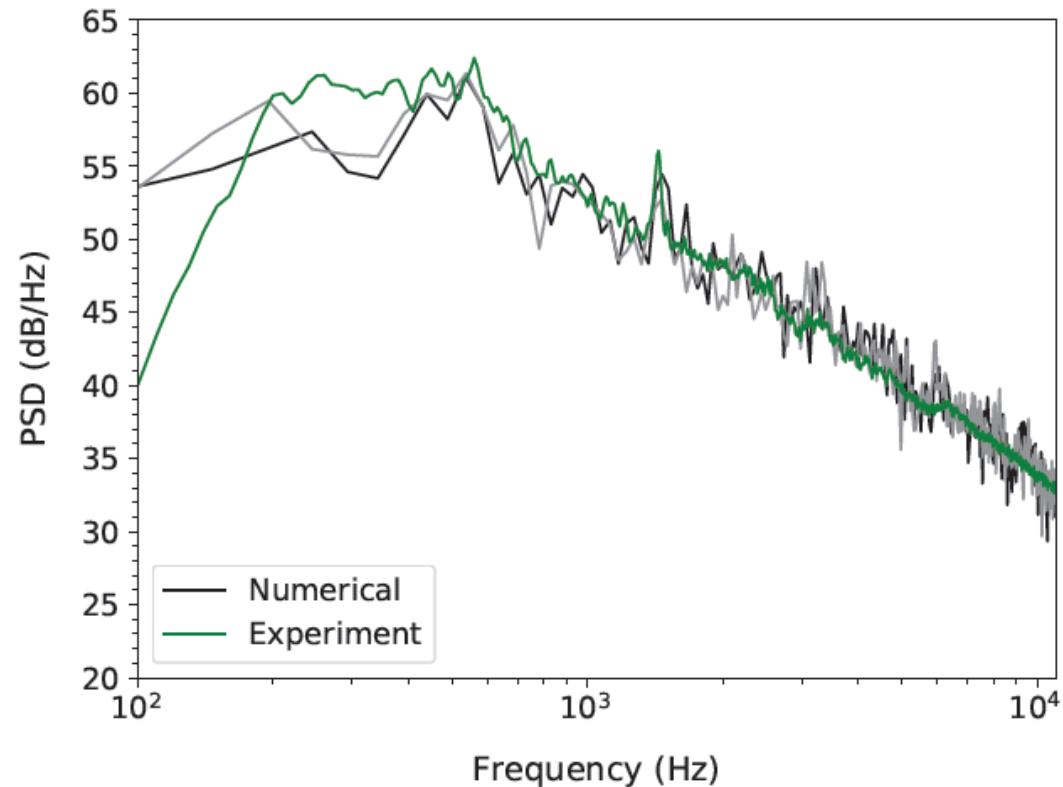
Adapted from Manoha et al., 2009

Landing Gear Noise Prediction



Coherent
structures
from SPOD
at 1500 Hz

Far-field pressure
M6 microphone - sideline



Ffowcs Williams & Hall Analogy

- Lighthill showed that free turbulence radiates noise with $\bar{p}'^2 \sim M^8$ while Curle showed that a compact surface radiates noise with $\bar{p}'^2 \sim M^6$
- Ffowcs Williams & Hall investigated the case of turbulence in the proximity of a trailing edge

$$\nabla^2 \hat{p}' + k^2 \hat{p}' = - \left[\widehat{\frac{\partial^2 \rho u_i u_j}{\partial x_i \partial x_j}} \right] \quad k = \frac{\omega}{c_0}$$

Non-homogeneous Helmholtz equation;
quiescent medium

Ffowcs Williams & Hall Analogy

- Acoustic scattering problem needs to be solved

$$\nabla^2 G + k^2 G = \delta(\mathbf{x} - \mathbf{y}) \longrightarrow \text{Green's function: fundamental solution of Helmholtz eqn.}$$

Making use of Green's second theorem one can write

$$\int_V G \nabla^2 \hat{p}' - \hat{p}' \nabla^2 G dV = \oint_S G \frac{\partial \hat{p}'}{\partial \mathbf{n}} - \hat{p}' \frac{\partial G}{\partial \mathbf{n}} dS$$

$$\hat{p}'(\mathbf{x}, \omega) = \underbrace{\oint_S G \frac{\partial \hat{p}'}{\partial \mathbf{n}} - \hat{p}' \frac{\partial G}{\partial \mathbf{n}} dS}_{\text{scattered sound}} + \underbrace{\int_V G \frac{\partial^2 \widehat{\rho u_i u_j}}{\partial x_i \partial x_j} dV}_{\text{incident sound}}$$

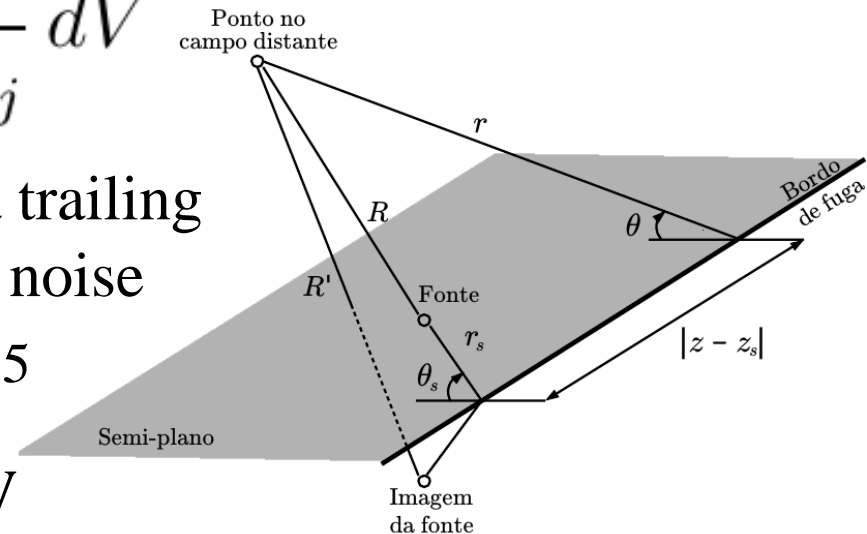
Ffowcs Williams & Hall Analogy

- If we look for the Green's function that gives $\partial G / \partial \mathbf{n} = 0$
- We know that for a rigid surface $\partial \hat{p}' / \partial \mathbf{n} = 0$
- Ffowcs Williams & Hall equation provides

$$\hat{p}'(\mathbf{x}, \omega) = \int_V \widehat{\rho u_i u_j} \frac{\partial^2 G}{\partial x_i \partial x_j} dV$$

Turbulent eddy in the proximity of a trailing edge is a good model for TBL airfoil noise

- important result: $\bar{p}'^2 \sim M^5$
- cardioid shape directivity



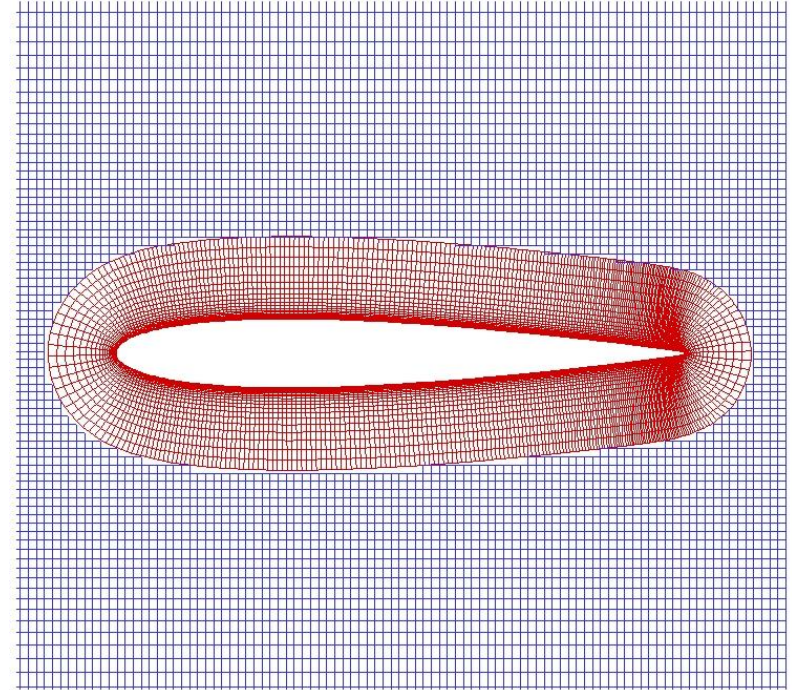
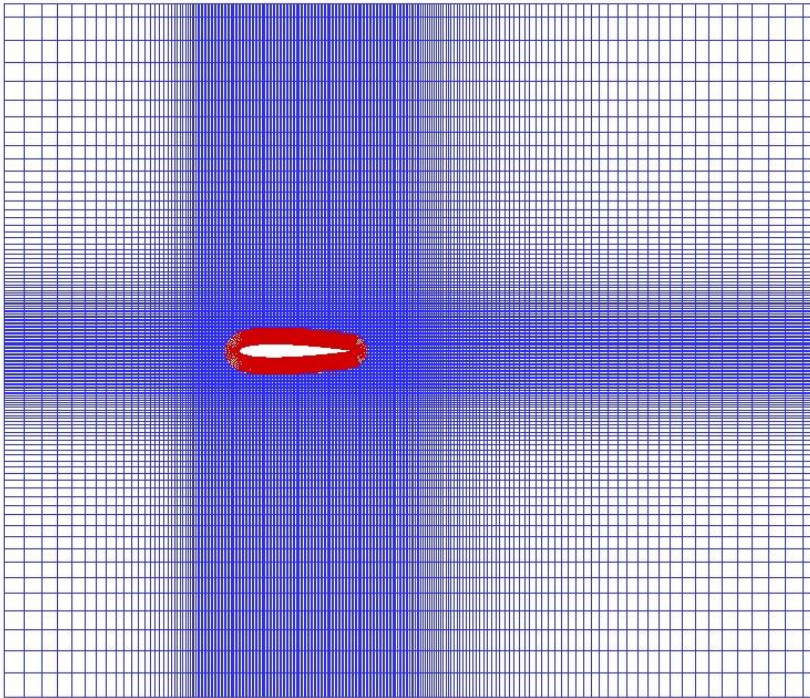
Airfoil Noise Prediction

Airfoil Noise Prediction

- **General curvilinear form of compressible Navier-Stokes equations**
- **Spatial discretization:** 6th order compact scheme on staggered grid plus 6th order compact schemes for filtering and interpolation
- **Overset grid:** 4th order Hermitian interpolation
- **Time integration:** Near-wall region – implicit 2nd order Beam-Warming scheme; Away from solid boundaries – 3rd order Runge-Kutta scheme
- **Unresolved turbulent scales:** Dynamic SGS model
- **Noise prediction:** Ffowcs Williams and Hawkings acoustic analogy

Airfoil Noise Prediction

$Re_c = 408000$, $Ma_\infty = 0.115$, $AOA = 0$ deg.

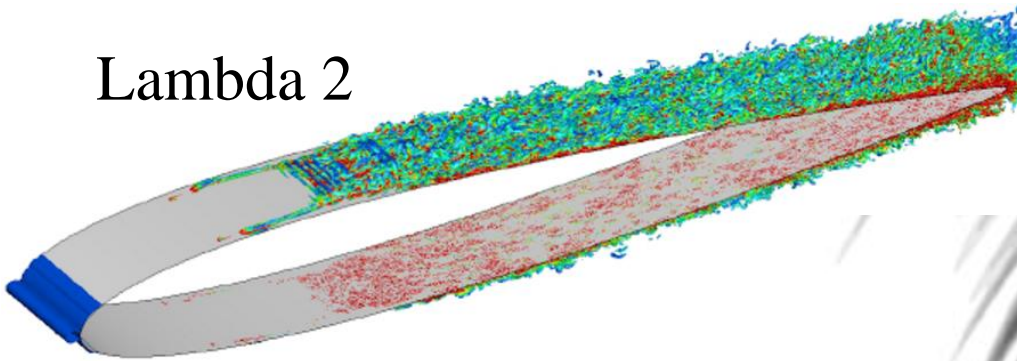


Every 4-th grid point
O-grid block – $1536 \times 125 \times 128$
Background grid block – $896 \times 511 \times 64$

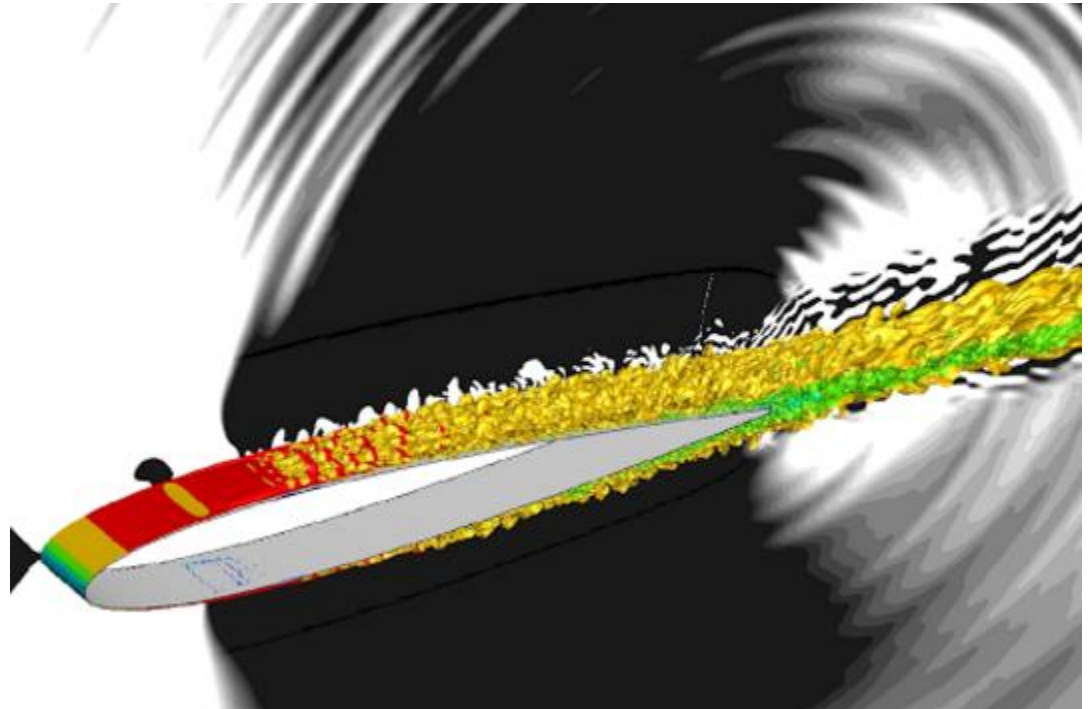
Airfoil Noise Prediction

$Re_c = 408000$, $Ma_\infty = 0.115$, $AOA = 0$ deg.

Lambda 2

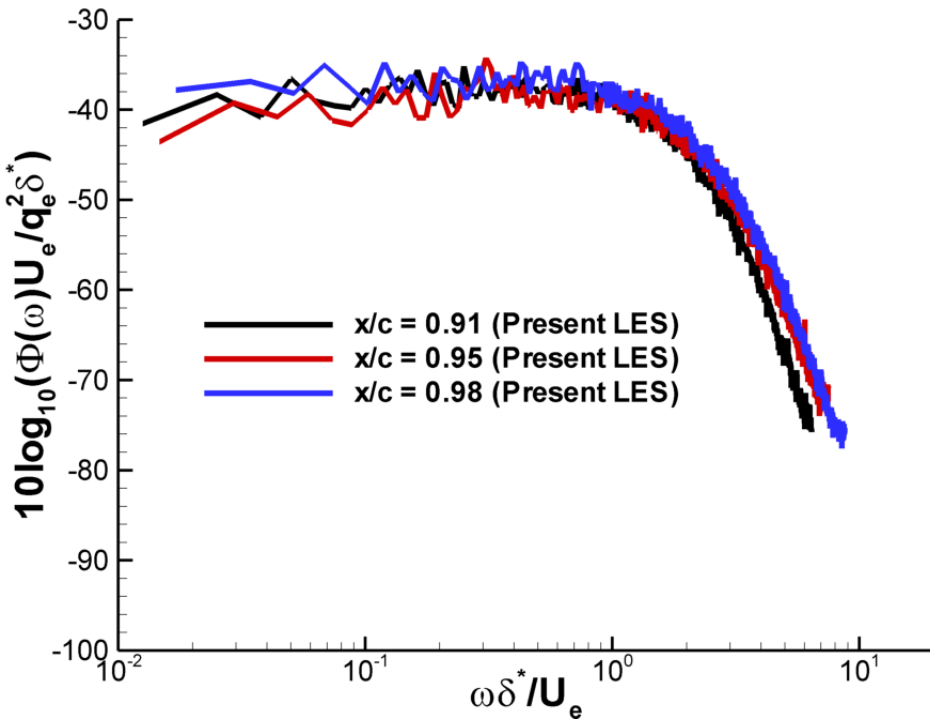


Iso-surfaces of
vorticity plus
dilatation field

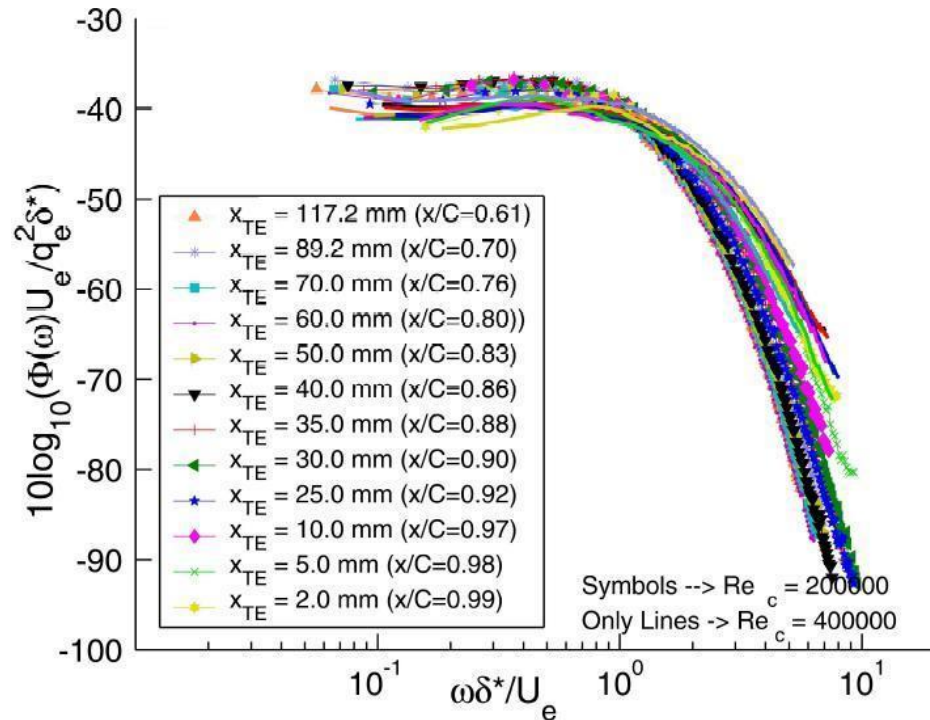


Airfoil Noise Prediction

Wall pressure PSD normalized by outer variables



Present LES

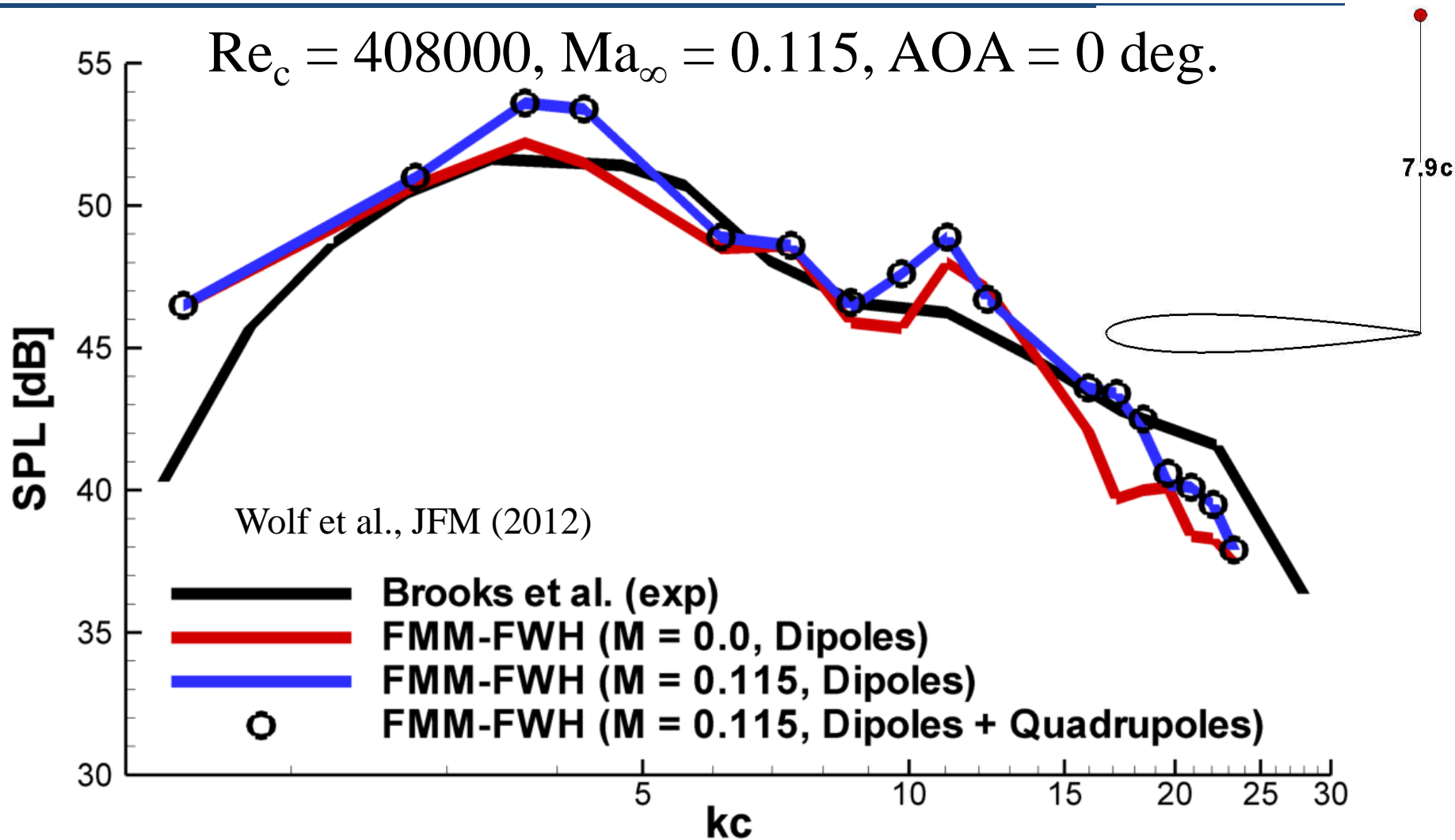


Experiments from Sagrado and Hynes^[1]

[1] Sagrado and Hynes, Fluids and Structures, Vol. 30, 2012, pp. 3-34

Airfoil Noise Prediction

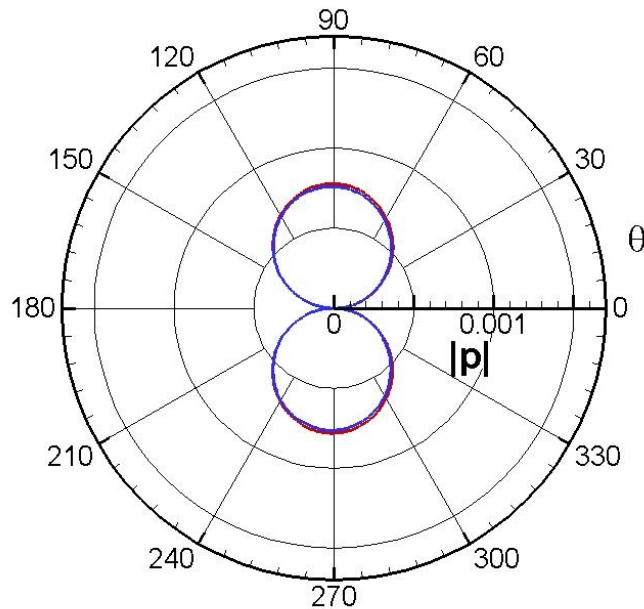
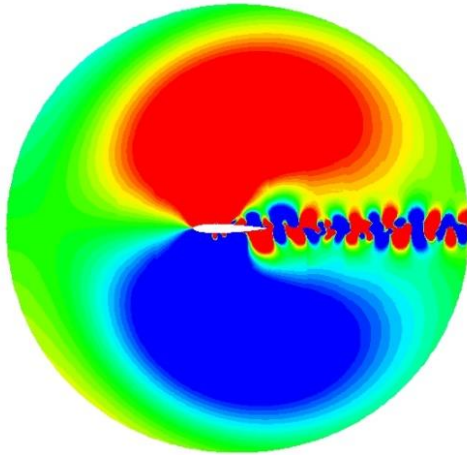
$Re_c = 408000$, $Ma_\infty = 0.115$, $AOA = 0$ deg.



[1] Brooks et al., NASA Publication, 1989

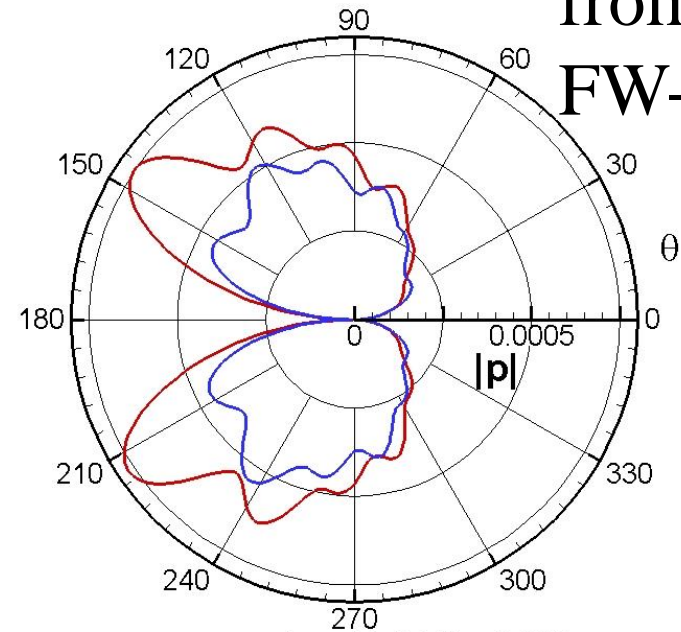
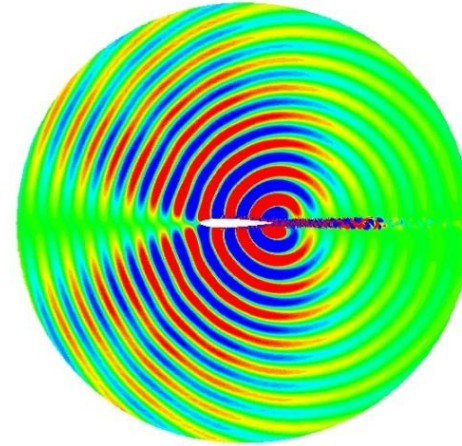
Airfoil Noise Prediction

“dipolar”
directivity
from
Curle



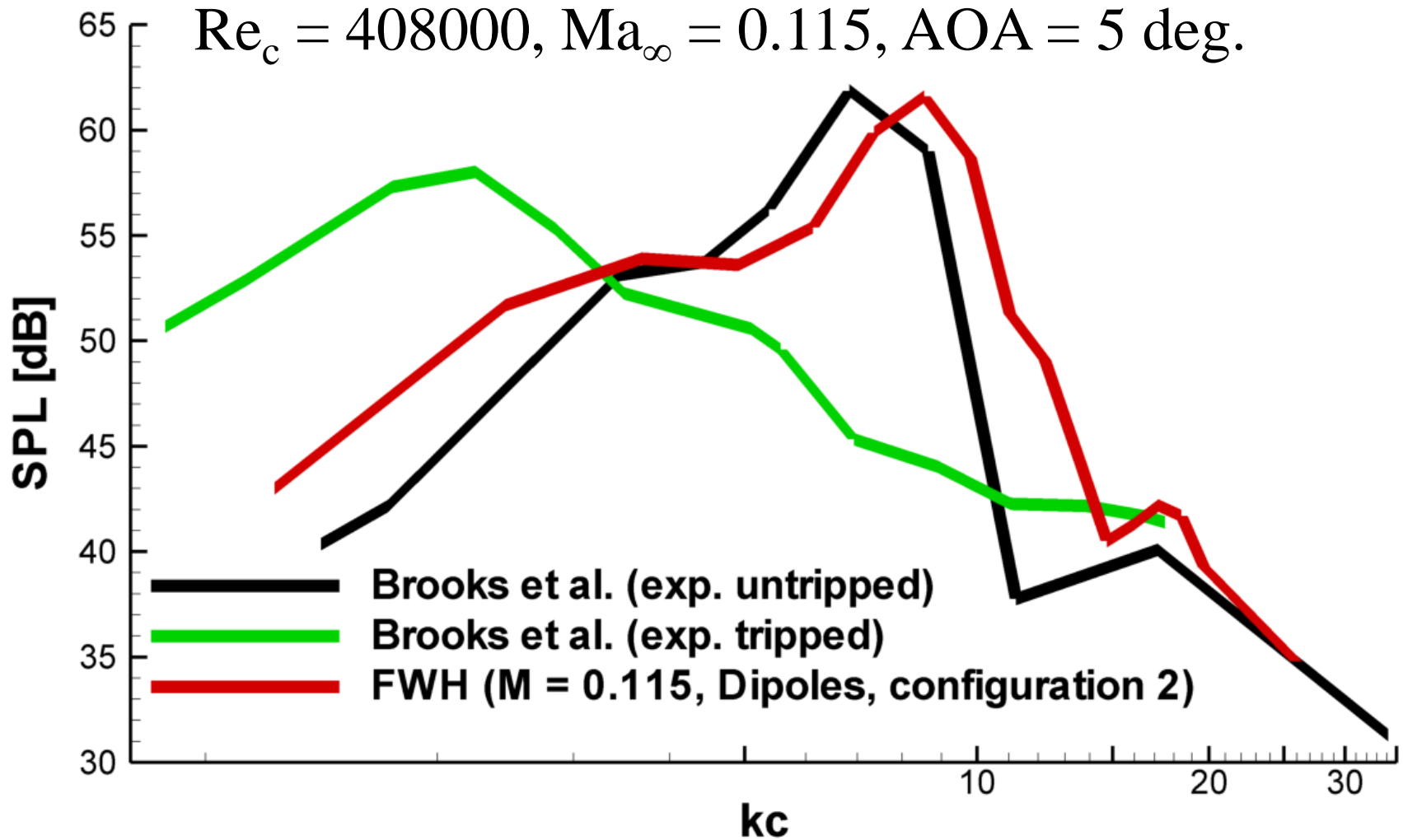
— $kc = 1.51; M = 0.115$
— $kc = 1.51; M = 0.0$

“cardioid”
directivity
from
FW-Hall



— $kc = 18.47; M = 0.115$
— $kc = 18.47; M = 0.0$

Airfoil Noise Prediction

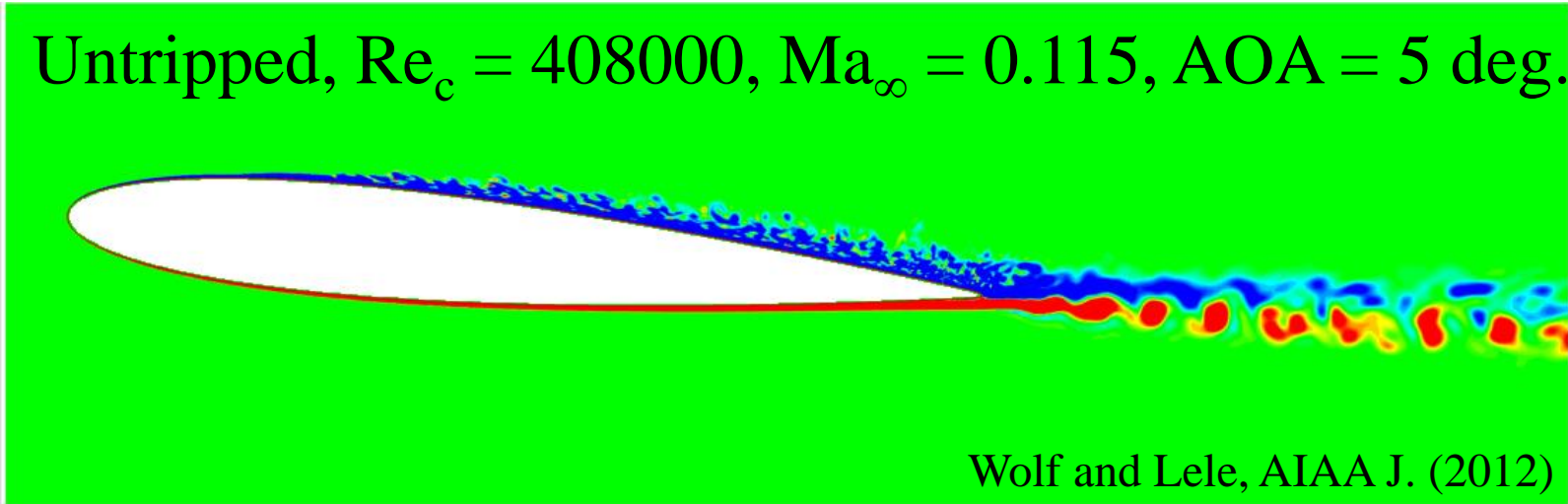


Sound pressure level at $x = c$, $y = 7.9c$ and mid-span

[1] Brooks *et al.*, NASA Publication, 1989

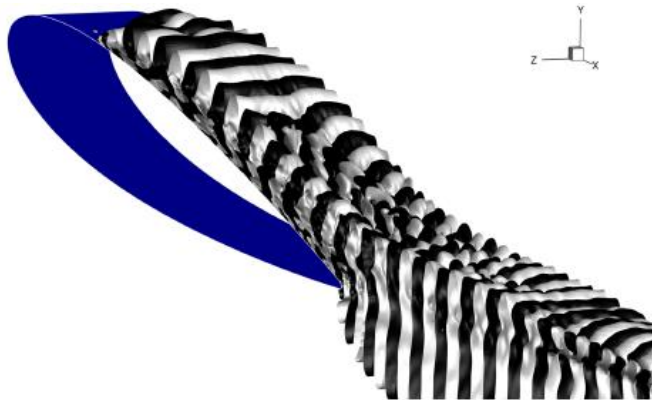
Airfoil Noise Prediction

Untripped, $Re_c = 408000$, $Ma_\infty = 0.115$, $AOA = 5$ deg.



Wolf and Lele, AIAA J. (2012)

1st POD mode, TKE norm



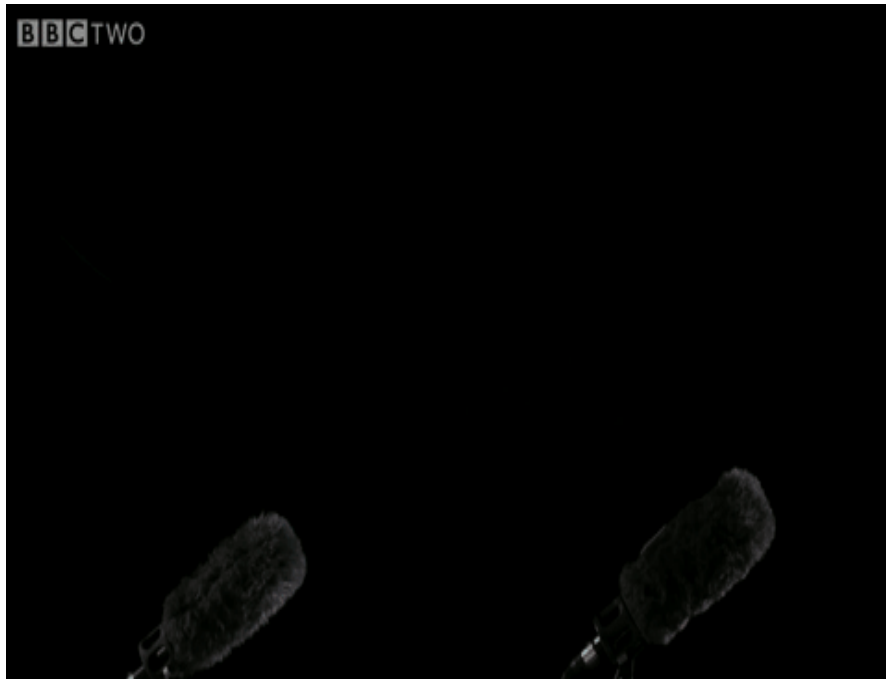
1st SPOD mode, TKE norm



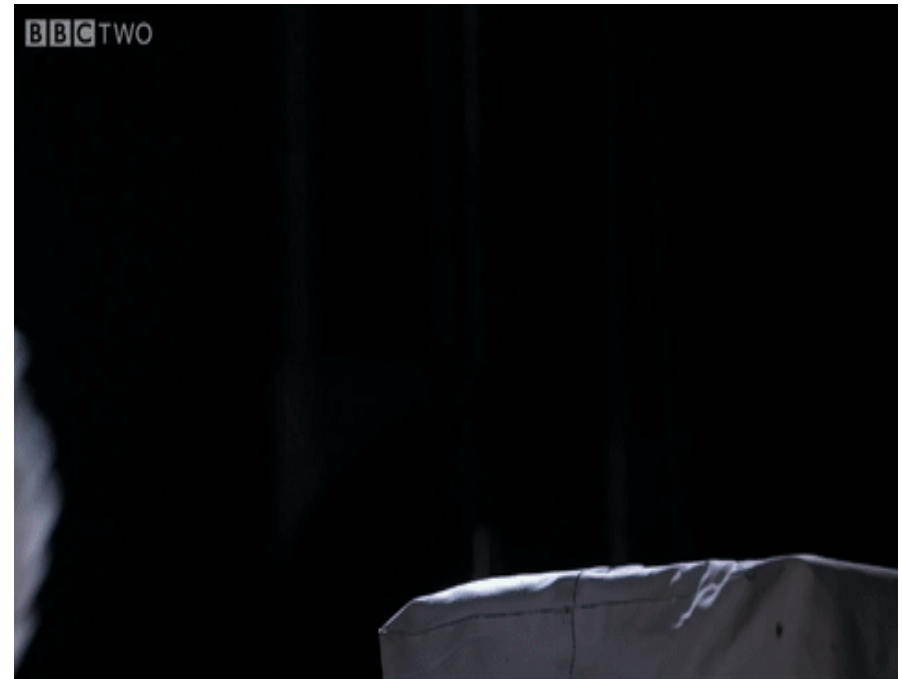
Ribeiro and Wolf, PoF (2017)

Poro-Elastic Trailing Edges

Pigeon



Owl

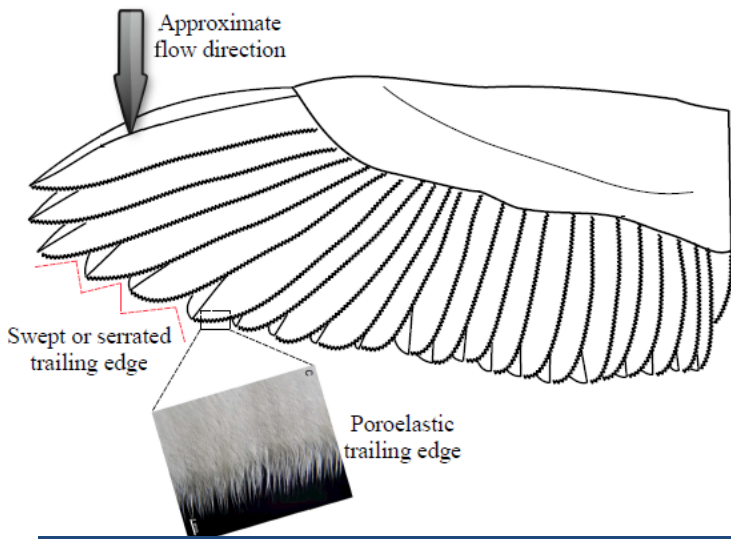


BBC TWO – Natural World 2015-2016, Super Powered Owls - Flying silently

Poro-Elastic Trailing Edges



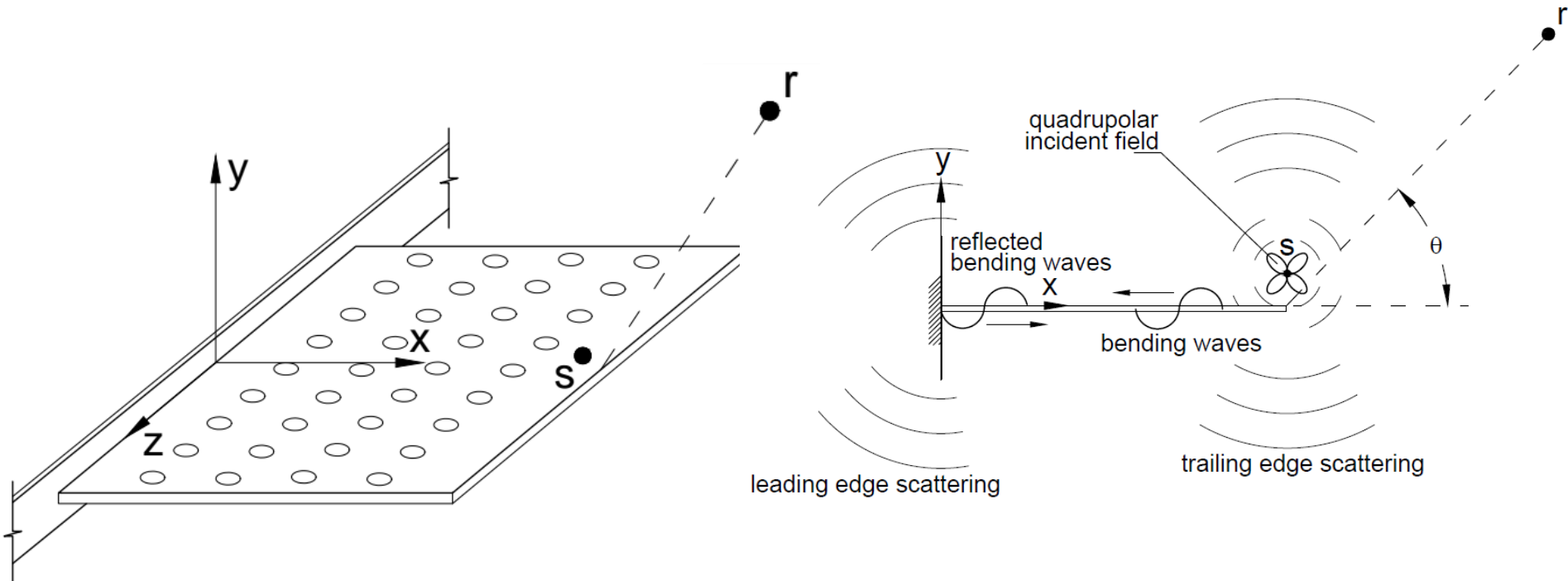
Owls are silent hunters



- Owls possess the ability to fly and hunt silently
- Their low self-noise is due to serrated trailing-edge and poro-elastic feather structure
- Several authors studied the reduction in noise scattering by application of porosity and elasticity assuming semi-infinite extent of elastic or poro-elastic edge

Poro-Elastic Trailing Edges

Problem description



Wolf and Cavalieri, AIAA P (2015)

Poro-Elastic Trailing Edges

- Three equations coupled:
 - Vibration of plate subject to acoustic load
 - Acoustic scattering due to noise source
 - Euler equation for coupling between fluid and structure

$$(1 - \alpha_H) \nabla^4 \eta - \frac{k_0^4}{\Omega^4} \eta = (1 + \alpha_H K_R) \frac{\epsilon}{\Omega^6} k_0^3 \Delta p$$

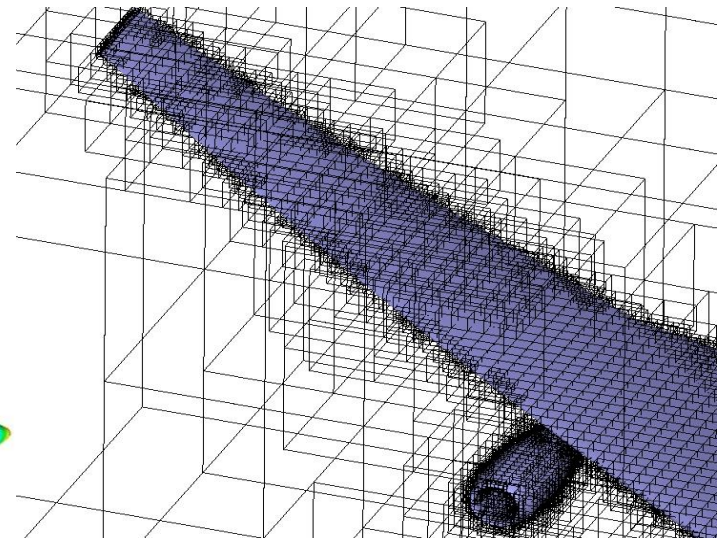
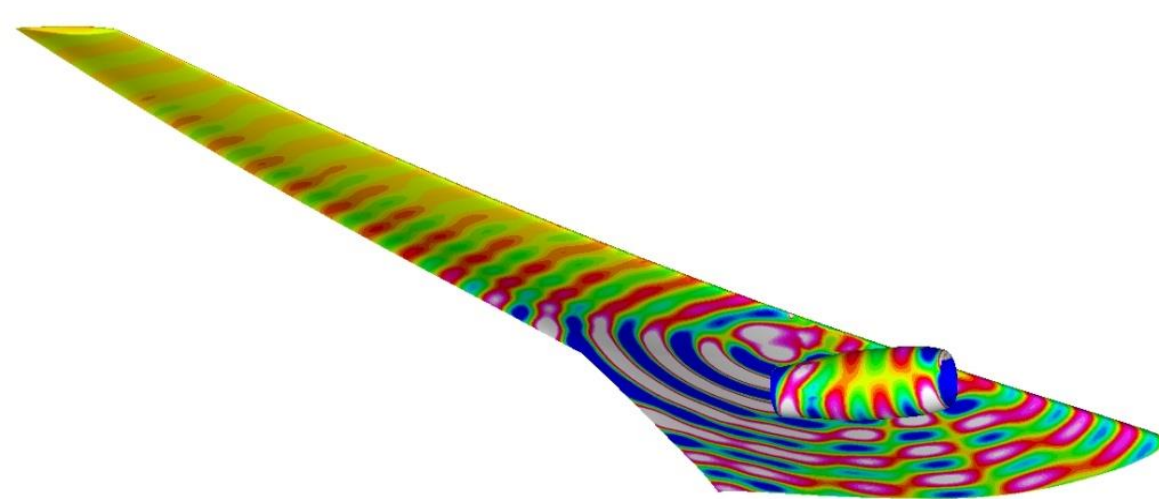
$$\Omega = (\tilde{\omega} / \tilde{\omega}_c)^{1/2} = \tilde{k}_0 / \tilde{k}_B \quad \nabla^2 p + k_0^2 p = -S$$

$$\epsilon = \frac{\tilde{\rho}_f \tilde{k}_0}{\tilde{m} \tilde{k}_B^2} \quad (1 - \alpha_H) k_0^2 \eta - \frac{\alpha_H K_R}{2R} \Delta p = \left. \frac{\partial p}{\partial y} \right|_{y=0}$$

Poro-Elastic Trailing Edges

Numerical methodology for 3D problem

- Vibration problem solved *a priori*: structural modal basis obtained by finite-element method
- Acoustic problem solved using boundary element method accelerated by fast multipole method
- Euler equation provides boundary condition for BEM



Poro-Elastic Trailing Edges

Helmholtz integral equation

$$T(\mathbf{x})p(\mathbf{x}) = \int_{\Gamma} \left[\frac{\partial p(\mathbf{y})}{\partial n_y} G(\mathbf{x}, \mathbf{y}) - \frac{\partial G(\mathbf{x}, \mathbf{y})}{\partial n_y} p(\mathbf{y}) \right] d\Gamma - \frac{\partial^2 G(\mathbf{x}, \mathbf{z}_i)}{\partial \mathbf{z}_{i_m} \partial \mathbf{z}_{i_n}} S(\mathbf{z}_i)$$

Boundary condition

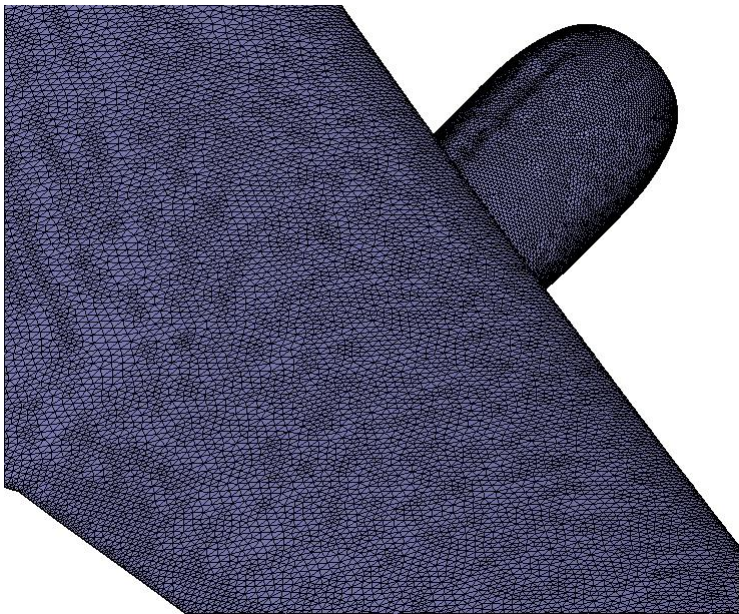
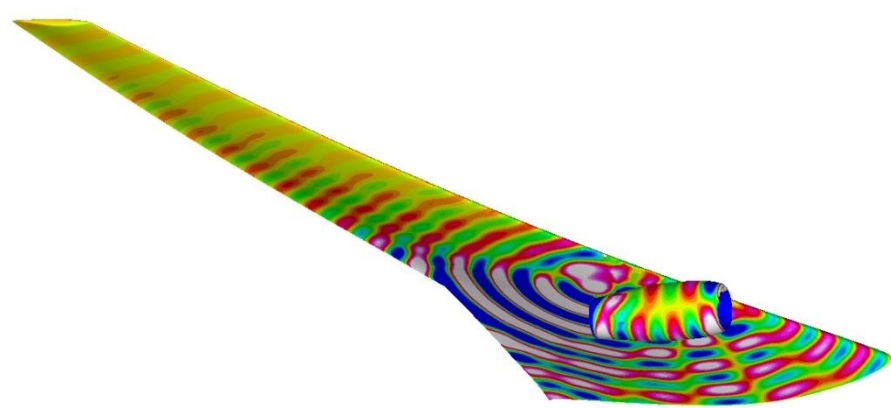
$$\left. \frac{\partial p}{\partial n} \right|_{\Gamma} = n_y \left. \frac{\partial p}{\partial y} \right|_{y=0} = n_y (1 + \alpha_H K_R) \frac{\epsilon k_0^5}{\Omega^6} \frac{\langle \Delta p(x), \phi_j \rangle}{\beta_j^4 - k_0^4 / (1 - \alpha_H) \Omega^4} \phi_j - n_y \frac{\alpha_H K_R}{2R} \Delta p$$

BEM Linear system

$$[H]\{p\} - [G] \left\{ \frac{\partial p}{\partial n} \right\} = \{S\} \longrightarrow ([H] - [G][D])\{p\} = \{S\}$$

$$D_{i,k} = (1 + \alpha_H K_R) \frac{\epsilon k_0^5}{\Omega^6} n_{y_i} n_{y_k} \gamma_k \sum_{j=1}^M \frac{\phi(x_k)_j \phi(x_i)_j}{\beta_j^4 - k_0^4 / (1 - \alpha_H) \Omega^4} - \frac{\alpha_H K_R}{2R} n_{y_i} (n_{y_k} \delta_{k,i} + n_{y_k} \delta_{k,N-i})$$

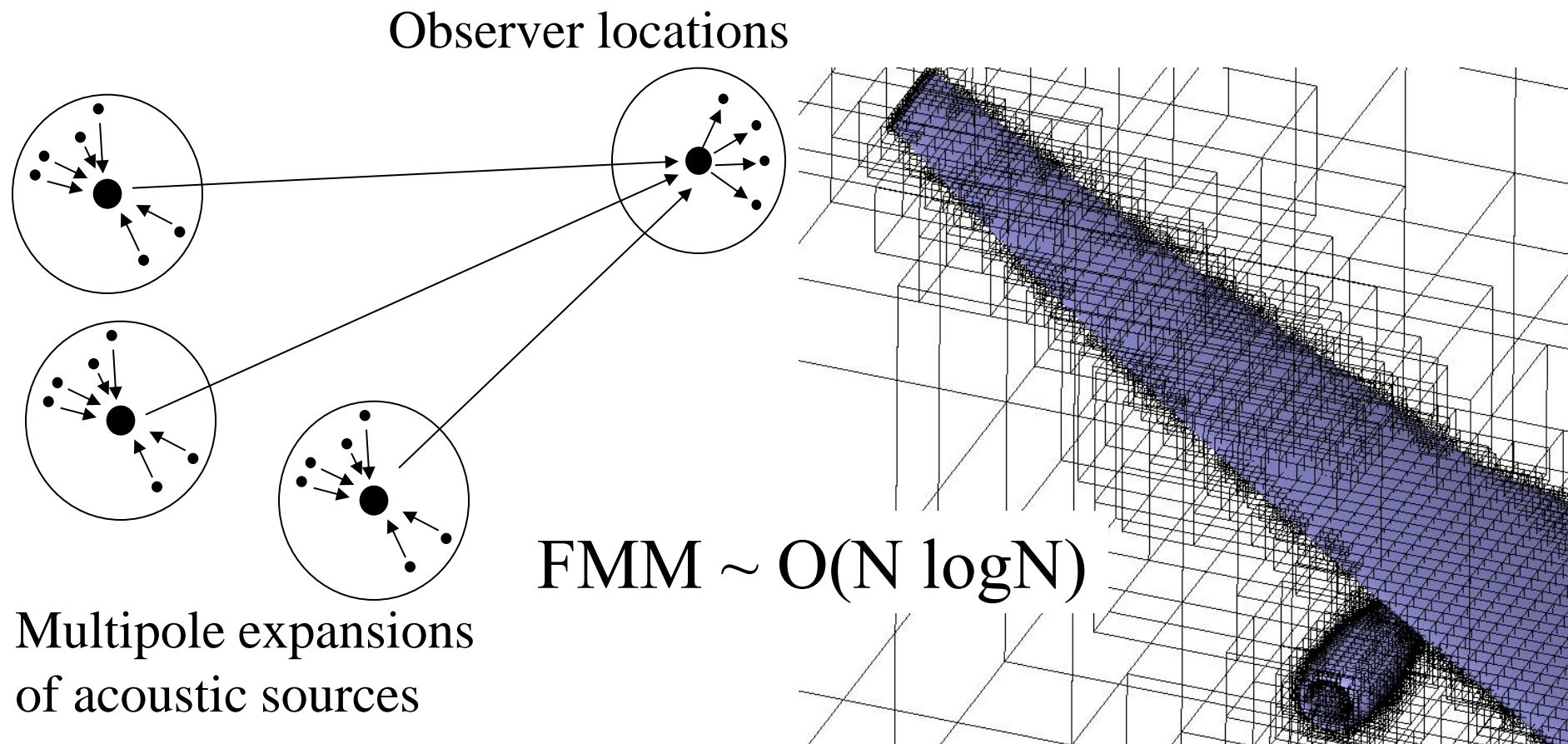
Poro-Elastic Trailing Edges



- Scattering and shielding of complex configurations
- simplified pre-processing
- accurate modeling of infinite domains
- no dispersion or dissipation of wave propagation
- large scale problems are expensive - $O(N^2)$

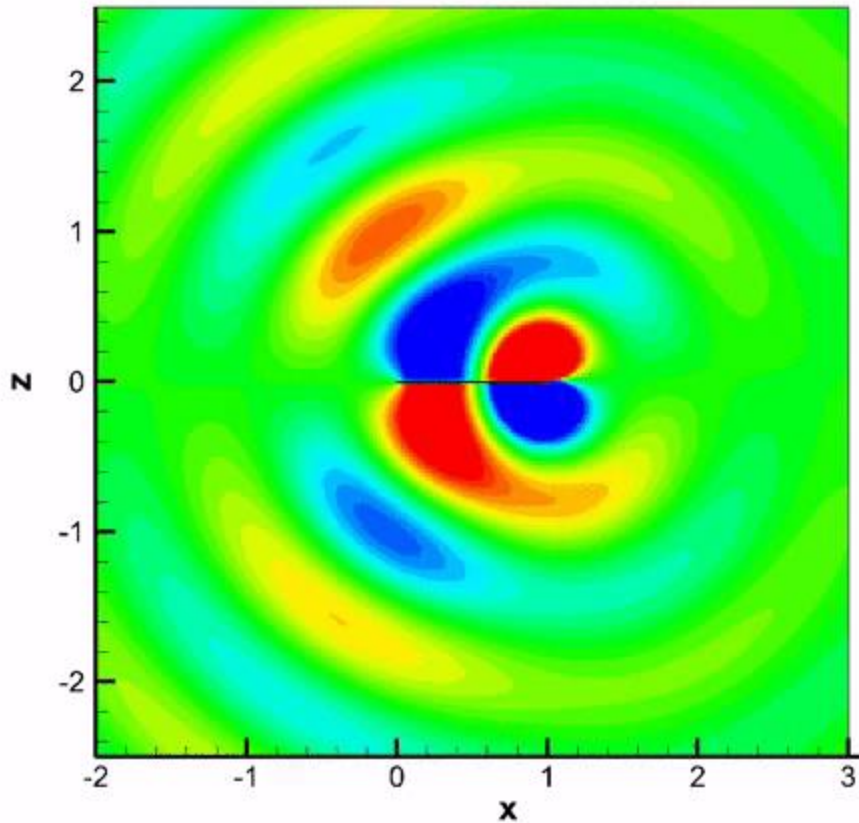
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- Clustering of acoustic sources at different spatial lengths
- Effects of distant clusters evaluated at observer locations

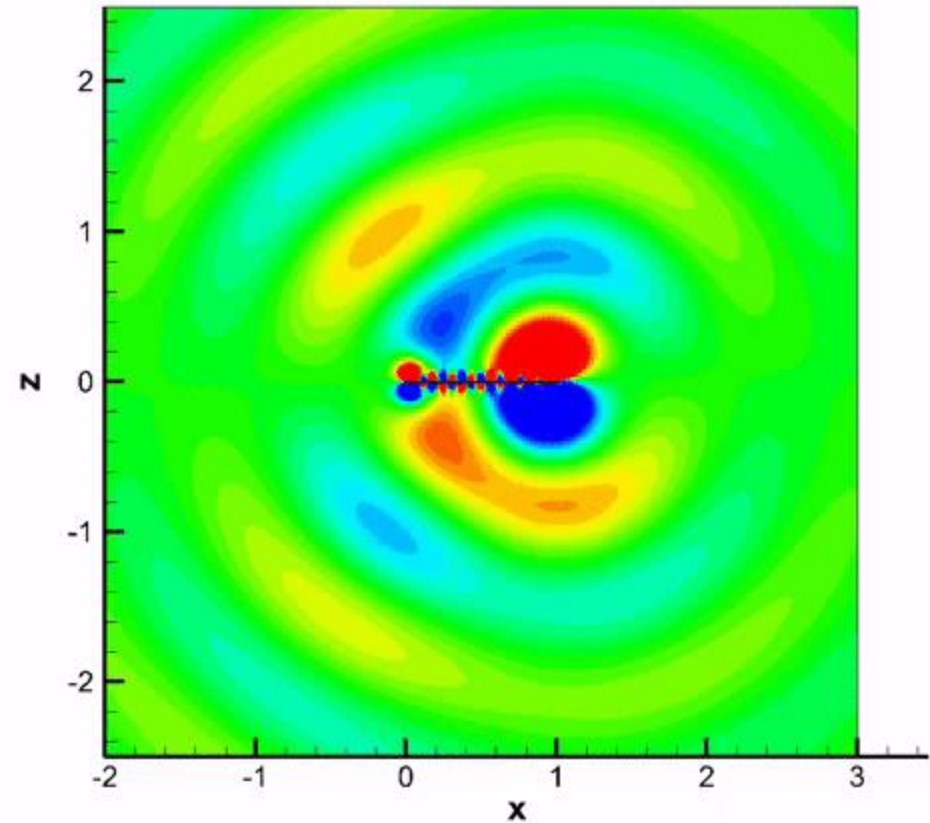


Poro-Elastic Trailing Edges

Acoustic pressure for $k_0 = 5$, $AR = 1$ – lateral view
3D quadrupole source placed at trailing edge



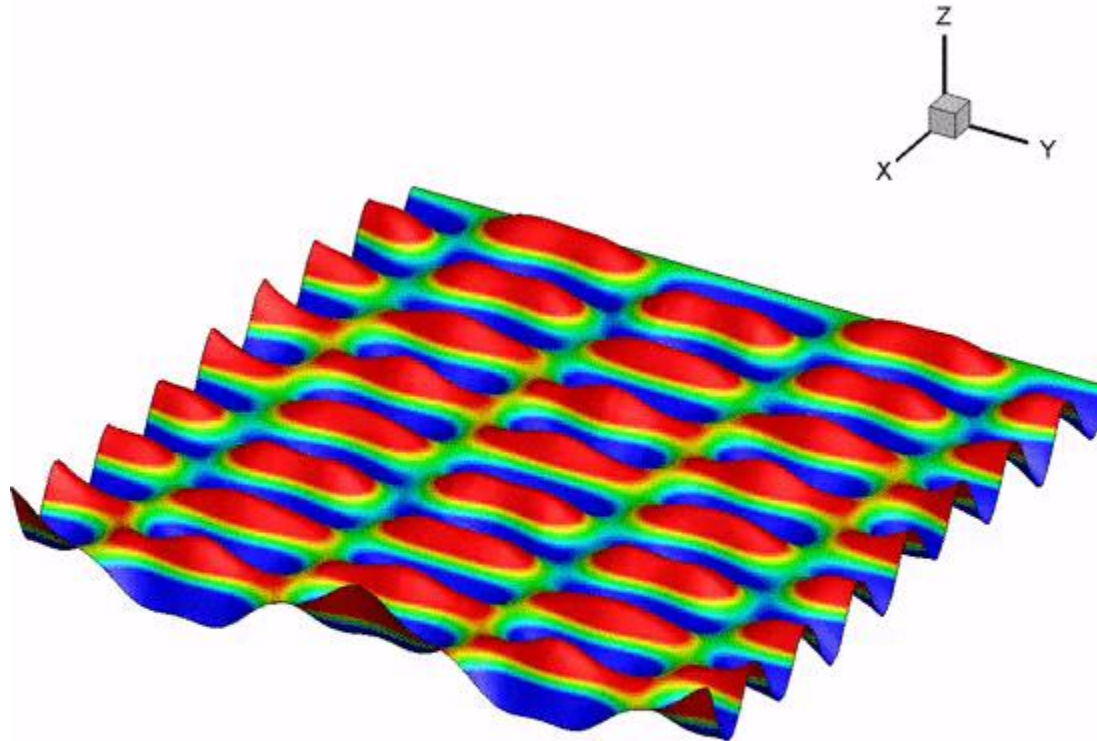
Rigid plate



Poroelastic plate $\Omega = 0.1$

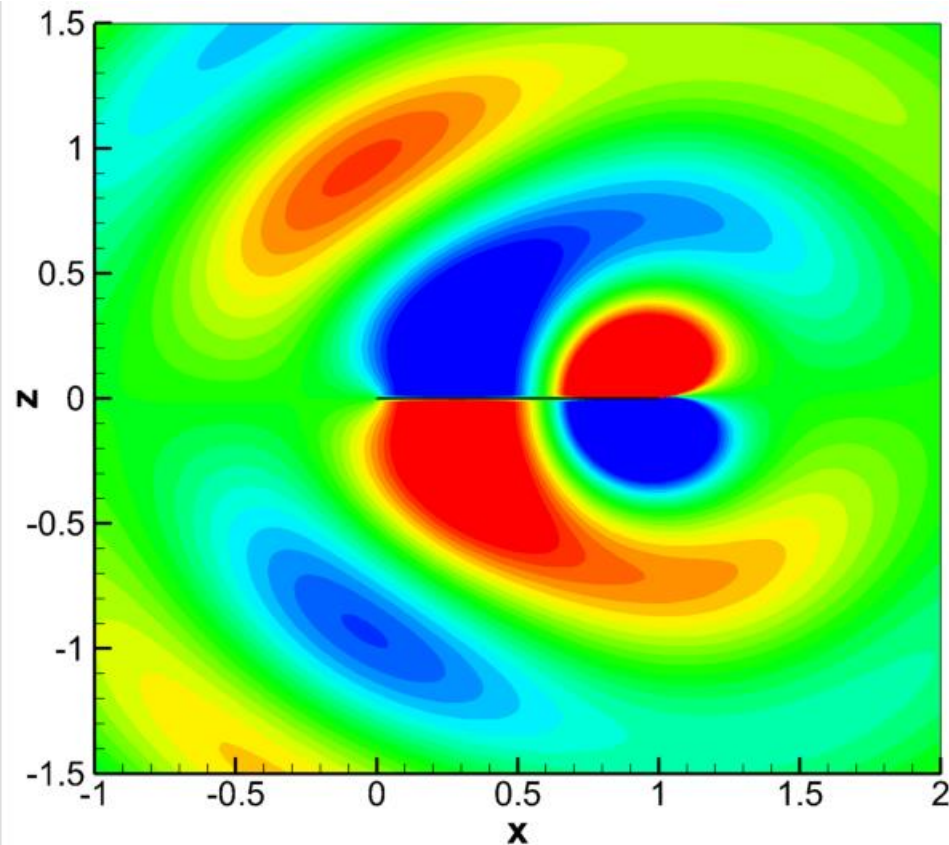
Poro-Elastic Trailing Edges

Plate displacement due to 3D source

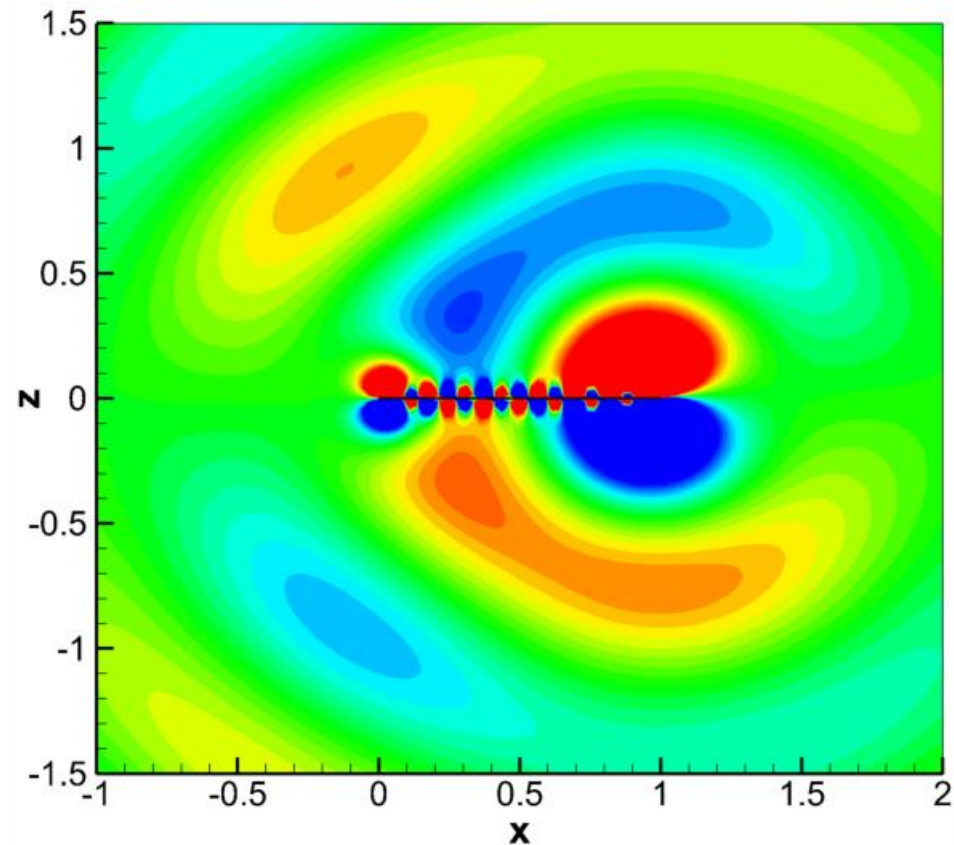


Poro-Elastic Trailing Edges

Acoustic pressure for $k_0 = 5$, $AR = 1$ – lateral view
3D quadrupole source placed at trailing edge



Rigid plate



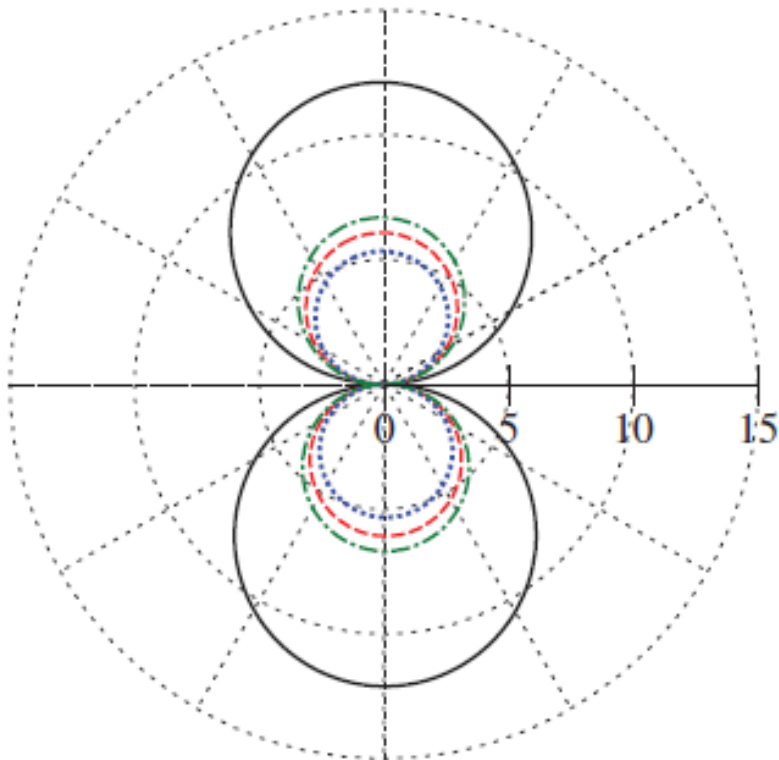
Poroelastic plate $\Omega = 0.1$

Poro-Elastic Trailing Edges

Finite poro-elastic plates

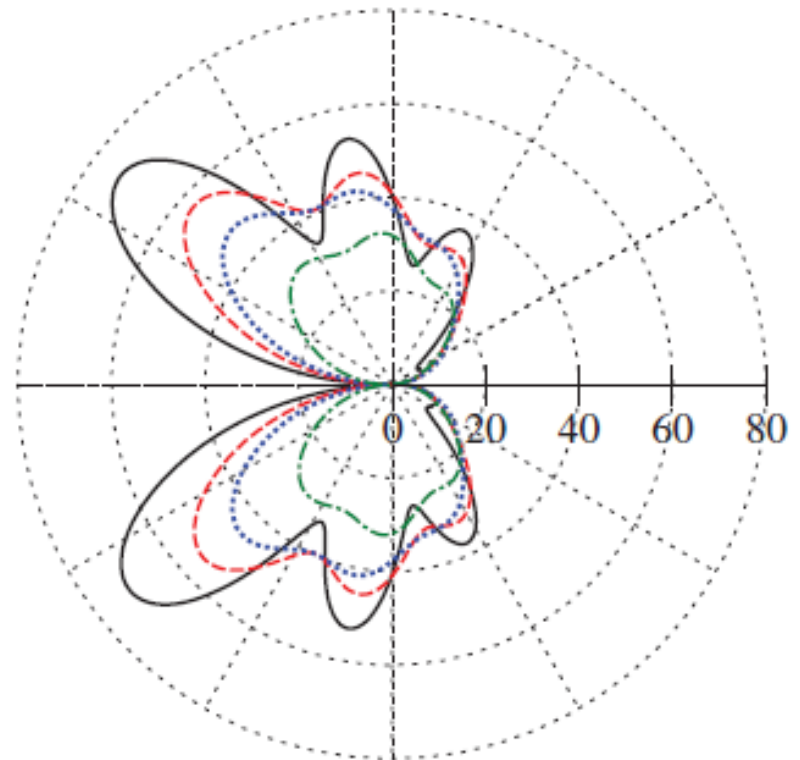
(a)

rigid, impermeable ———
 $\Omega = 0.04, k_B = 3.33$ - - - - -
 $\Omega = 0.025, k_B = 4.00$ ·····
 $\Omega = 0.18, k_B = 5.55$ - · - · -

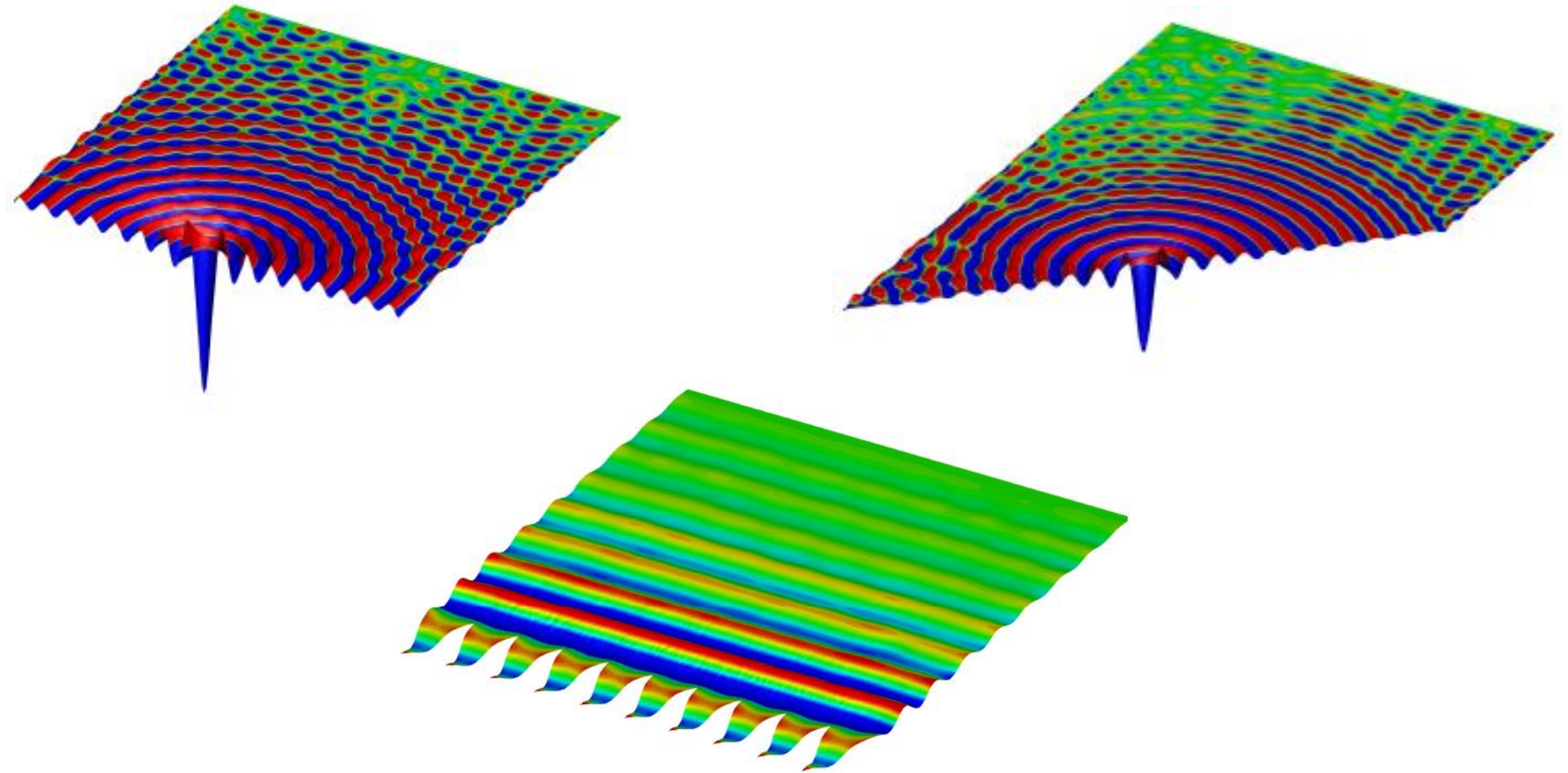


(b)

rigid, impermeable ———
 $\Omega = 0.25, k_B = 40.0$ - - - - -
 $\Omega = 0.12, k_B = 83.3$ ·····
 $\Omega = 0.06, k_B = 167$ - · - · -

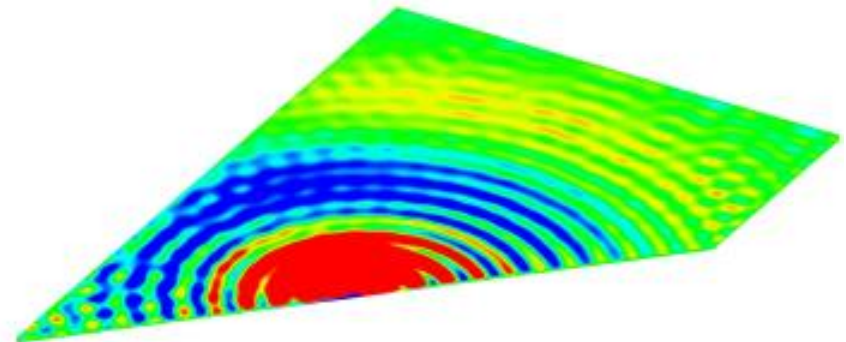
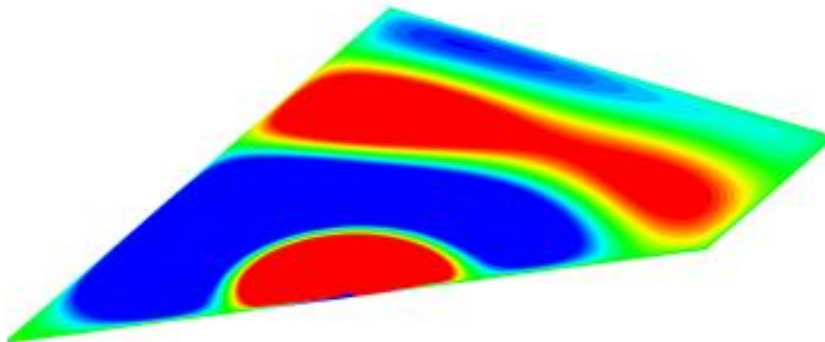
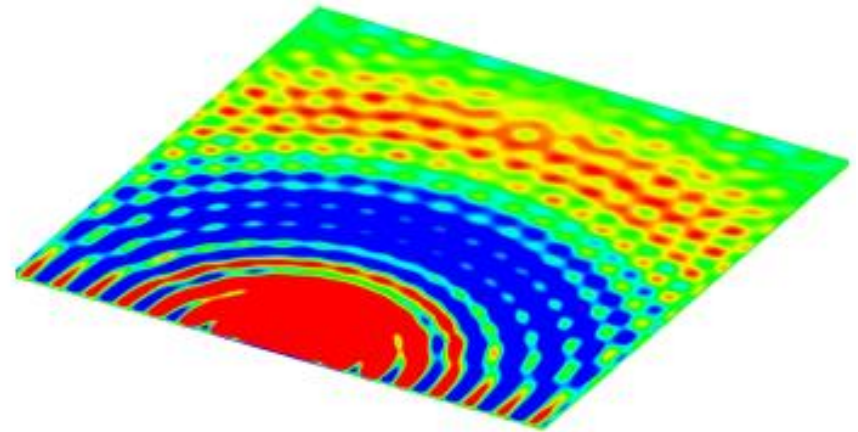
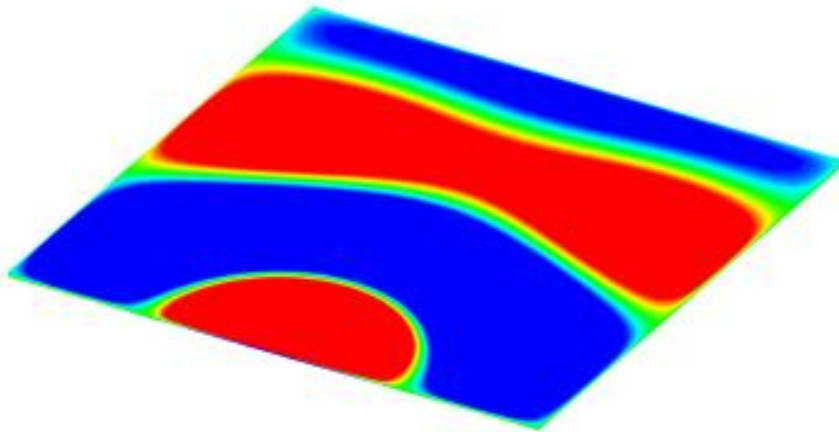


Poro-Elastic Trailing Edges



Acoustic scattering by poro-elastic plates with arbitrary geometry
Pimenta et al., JCP *in preparation*

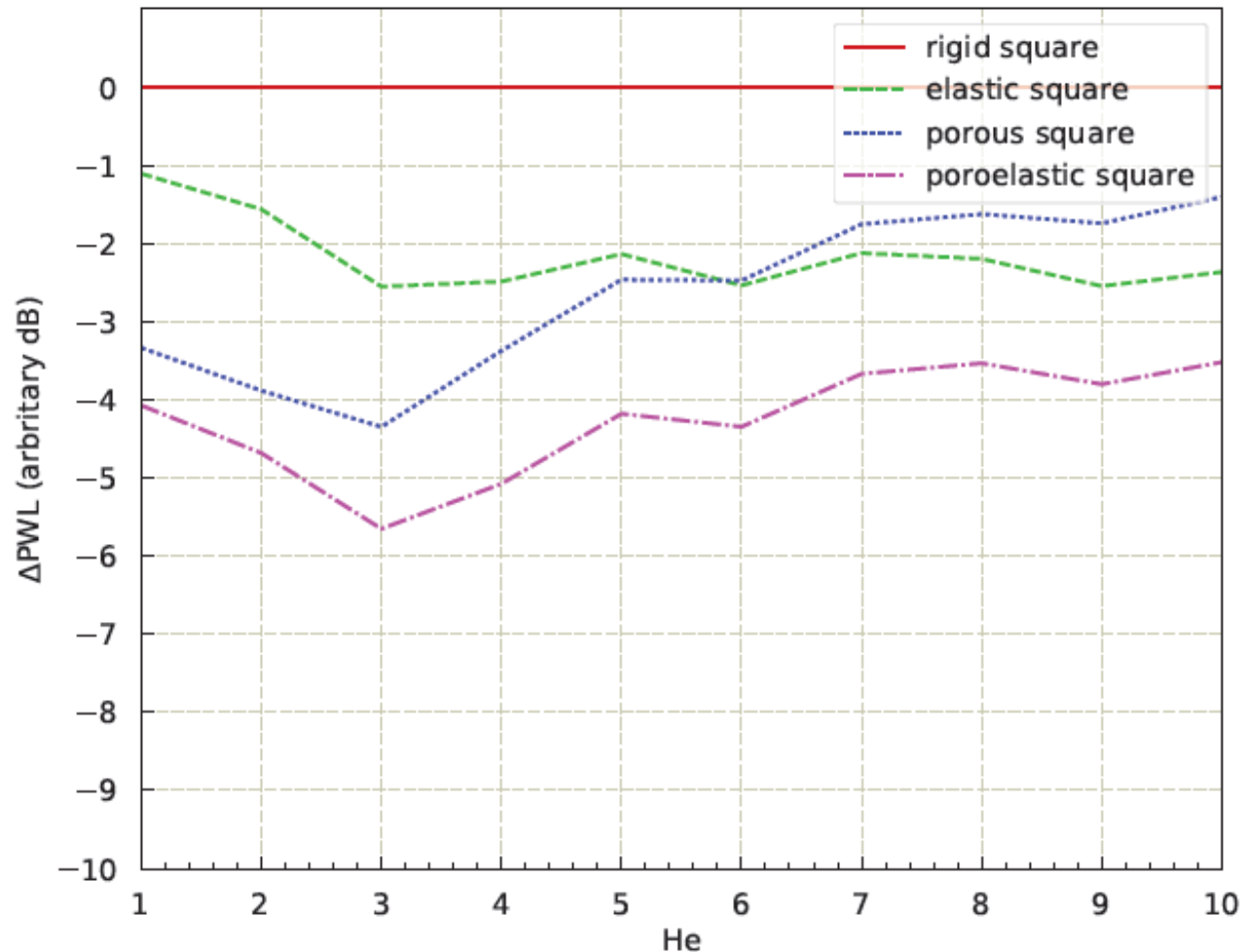
Poro-Elastic Trailing Edges



Destructive interference effects of acoustic surface pressure combined with trailing edge sweep reduce far-field noise

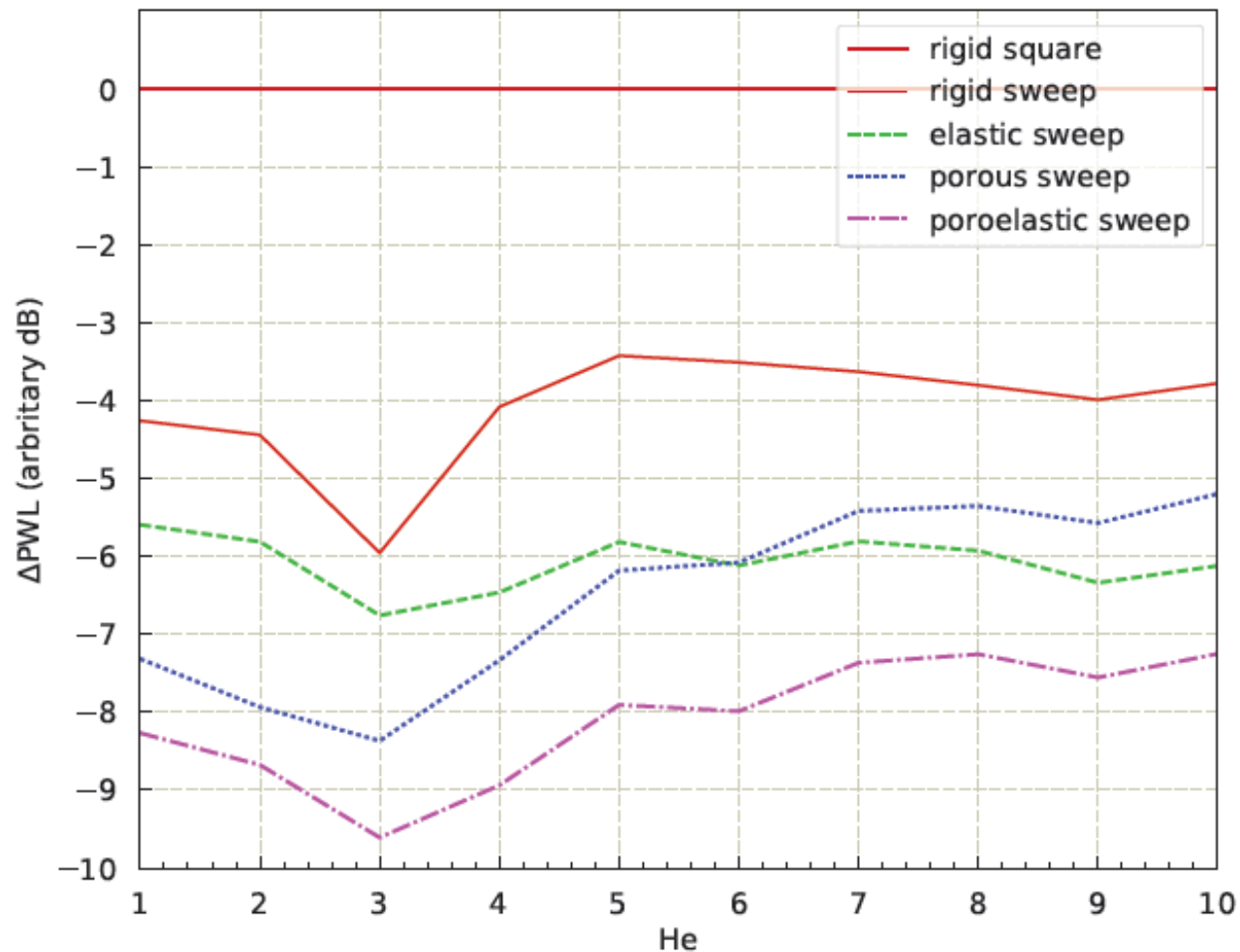
Poro-Elastic Trailing Edges

Sound power level in the far-field



Poro-Elastic Trailing Edges

Sound power level in the far-field



Acknowledgements



Motivation for Future Work?



Thank you!!!